

March 28, 2005



Introduction

- Dynamic Programming is a general algorithm design paradigm.
- Dynamic Programming is a technique for solving problems "bottom-up":
- first, solve small problems, and then use the solutions to solve larger problems.
- What kind of problems can Dynamic Programming solve efficiently?



Introduction

- Optimal substructure: The optimal solution contains optimal solutions to sub-problems.
- Overlapping sub-problems: the number of different sub-problems is small, and a recursive algorithm might solve the same sub-problem a few times.



Optimization problems

 Optimization problem is an important and practical class of computational problems.
 For most of these, the best known algorithm runs in exponential time.

Rabbits on an

By Leonard Si is 12th century

month

A pair of rabbits does not breed until they are two months old, then each pair produces another pair each month.

Rabbits on an

By Leonard Si is 12th century

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A pair of rabbits does not breed until they are two months old, then each pair produces another pair each month.

Rabbits on an By Leonard Tisa 12th centry

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month

Rabbits on an

By Leonard di Tisa 12th septury A pair of rabbits does not breed until they are two months old, then each pair produces another pair each month.

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By Leonard Si isa 12th century A pair of rabbits does not breed until they are two months old, then each pair produces another pair each month.



month

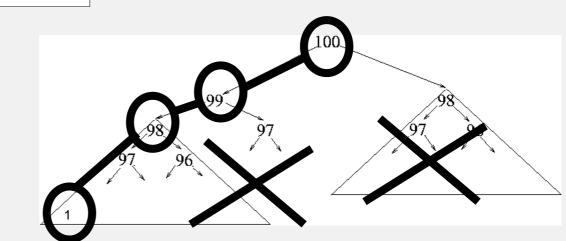
Rabbits on an By Leonard Si lisa 12th septury A pair of rabbits does not breed until they are two months old, then each pair produces another pair each month. month Assuming that no rabbits ever die, how many pairs of rabbits after *n* months.

Rabbits on an

By Leonard di lisa 12th septury

Fibonacci Number

 $F_{0} = 1$ $F_{1} = 1$ $F_{2} = F_{0} + F_{1} = 2$ $F_{3} = F_{1} + F_{2} = 3$ $F_{4} = F_{2} + F_{3} = 5$... $F_{n} = F_{n-2} + F_{n-1}$



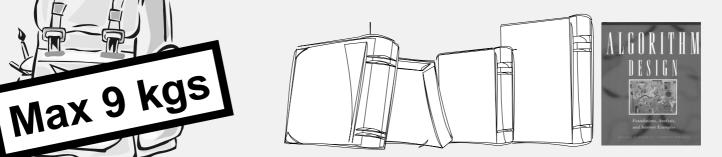
Exponential time \rightarrow Linear time

OVERLAPPING SUBPROBLEMS

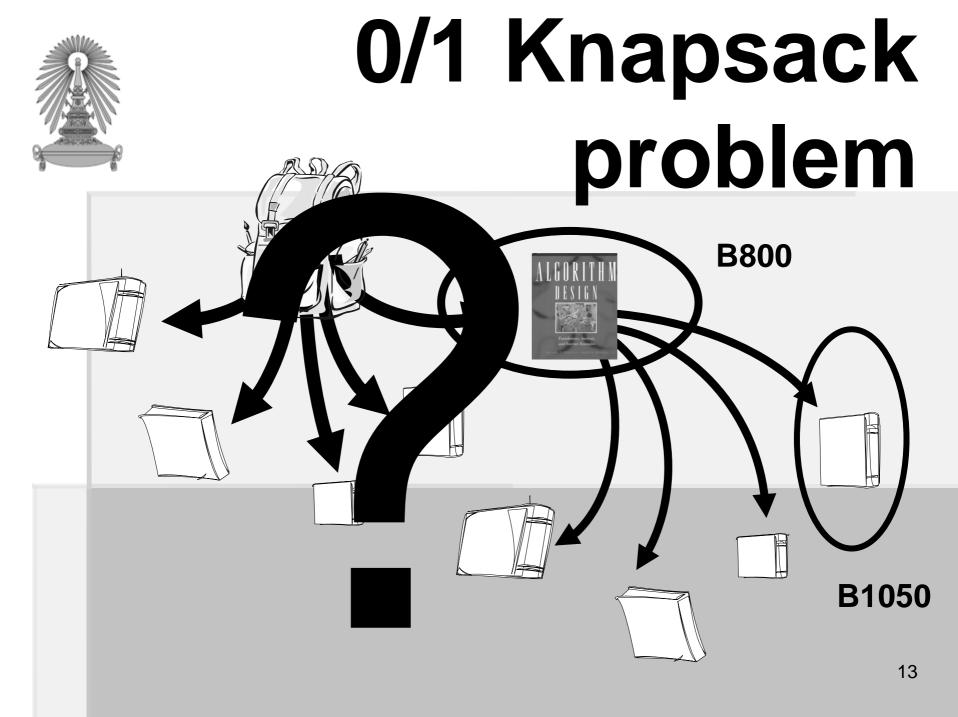


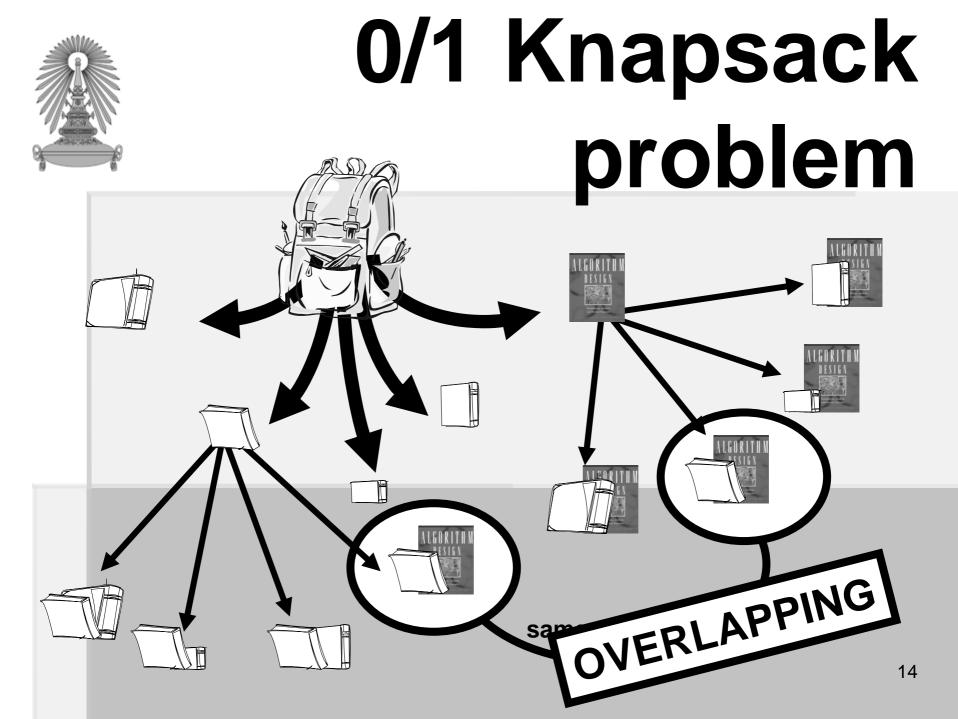
0/1 Knapsack problem

Choose items with maximum total benefit but with some limitation.



weight4 kgs2 kgs2 kgs6 kgs2 kgsvalueB200B30B60B250B800

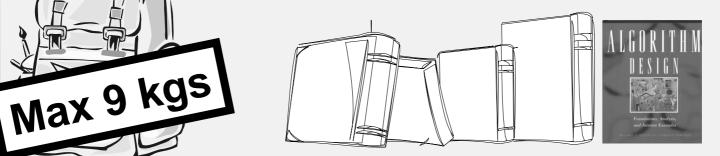






0/1 Knapsack problem

Choose items with maximum total benefit but with some limitation.



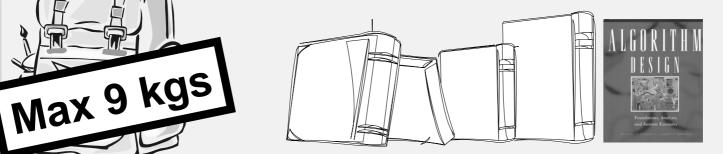
weight 4 kgs 2 kgs 2 kgs 6 kgs 2 kgs value B200 B30 B60 B250 B800

Number of solutions : 2ⁿ (n : number of books)

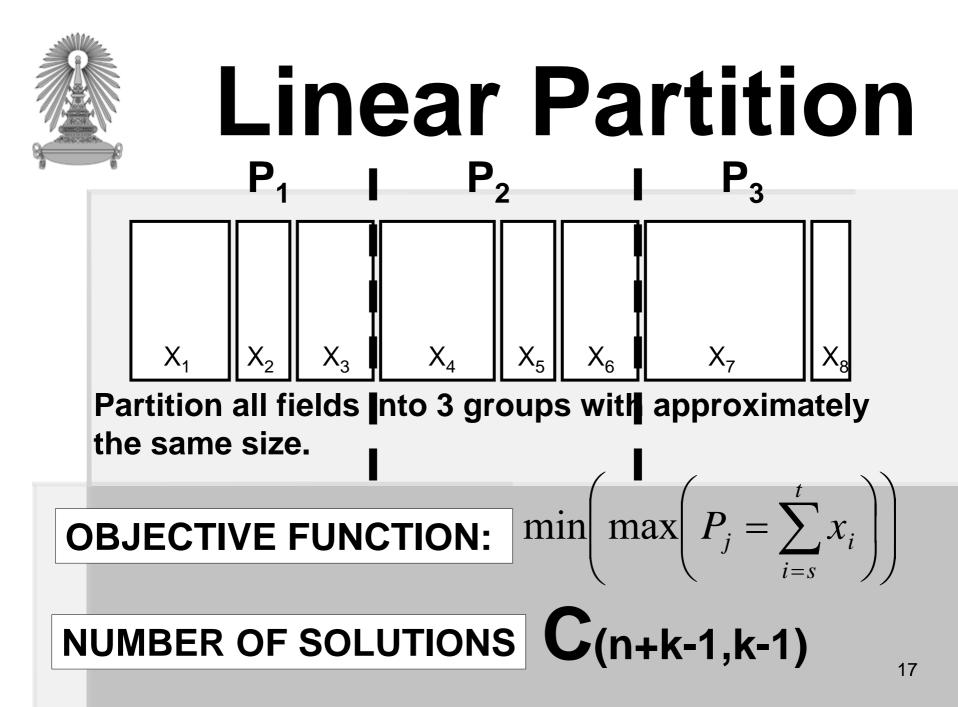


0/1 Knapsack problem

Choose items with maximum total benefit but with some limitation.



weight 4 kgs 2 kgs 2 kgs 6 kgs 2 kgs
value B200 B30 B60 B250 B800OBJECTIVE FUNCTION: $max(\sum_{i=1}^{n} x_i v_i))$ $x_i = \begin{cases} 1 & selected \\ 0 & otherwise \end{cases}$ $\sum_{i=1}^{n} x_i w_i \leq W$ CONSTRAINT16





 S_{1}

Printing neatly

	Application for word processor			
	Problem:	English text with <i>n</i> words		
		word <i>i</i> with length <i>w_i</i> (no.of.chars)		
		Each line contains max <i>M</i> chars		
	Solution:	Close to right justified text $(x_1, x_2, x_3,, x_m)$ x_j : last word th of line <i>j</i> .		
	Penalty: sum of right blank-end square.			
i	$M = M - \left[\left(x_i - (x_{i-1} + 1) \right) + \sum_{k=x_{i-1}+1}^{x_i} w_k \right] \text{ blank-end of line } i$			
		Objective function $\min\left(\sum_{k=1}^{k}S_{k}^{2}\right)$		



Given $M_1 M_2 M_3 M_4 \dots M_k$ with $d_{i-1} \times d_i$ dimension. Find an algorithm for

 $M_1 \times M_2 \times M_3 \times M_4 \times \ldots \times M_k$

Example:
$$A_{5\times10} \times B_{10\times20} \times C_{20\times1} \times D_{1\times10}$$

Cost of ((AB)C)D) is 1000+100+50 = 1150 Cost of ((AB)(CD) is 100 Cost of (A(B(C HON MANY SOLUTIONS 200 HON MANY SOLUTION 200 DOT 500 = 2700



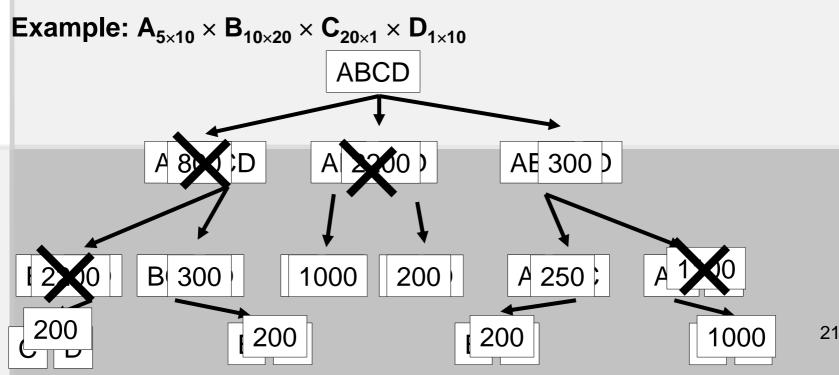
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Example: $A_{5\times10} \times B_{10\times20} \times C_{20\times1} \times D_{1\times10}$

Number of solutions = number of sequence of multiplication



Given $M_1 M_2 M_3 M_4 \dots M_k$ with $d_{i-1} \times d_i$ dimension. Find an algorithm for $M_1 \times M_2 \times M_3 \times M_4 \times \dots \times M_k$ Example: $A_{5 \times 10} \times B_{10 \times 20} \times C_{20 \times 1} \times D_{1 \times 10}$





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B

200

1000

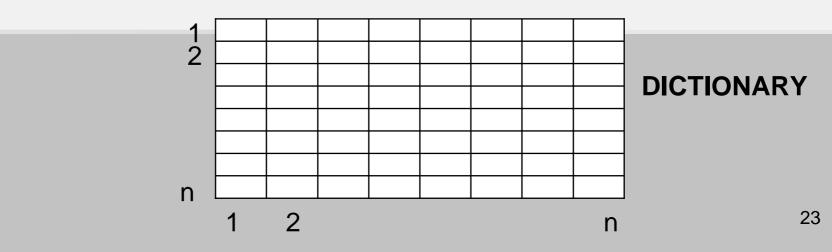


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 $M_1 \times M_2 \times M_3 \times M_4 \times \ldots \times M_k$

Let T_{i,i} be the cost of multiplication of M_i .. M_j

$$T_{i,j} = \min i \le k \le j - 1 \left(T_{i,k} + T_{k+1,j} + d_i \times d_k \times d_j \right)$$



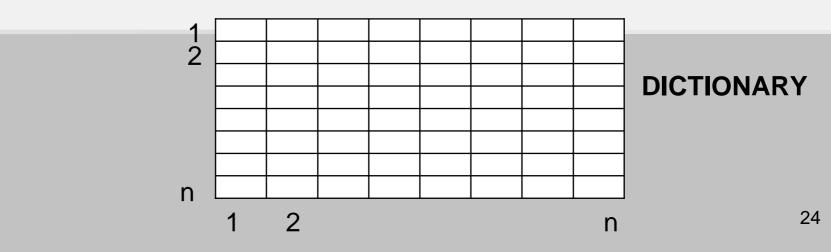


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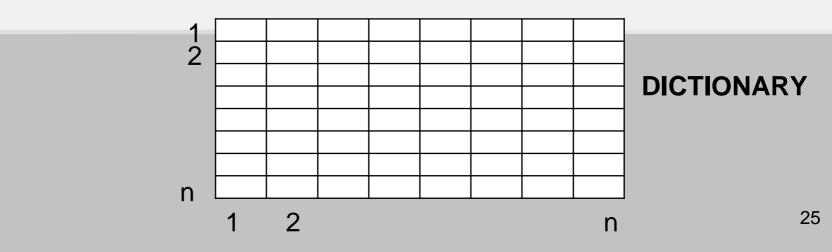


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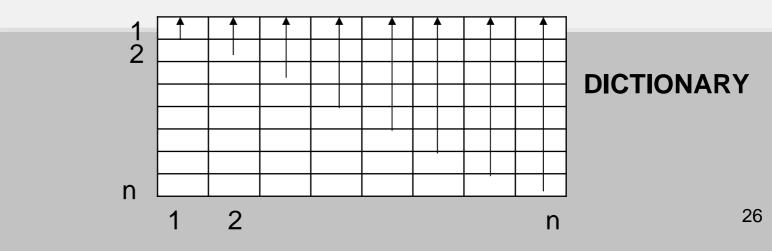


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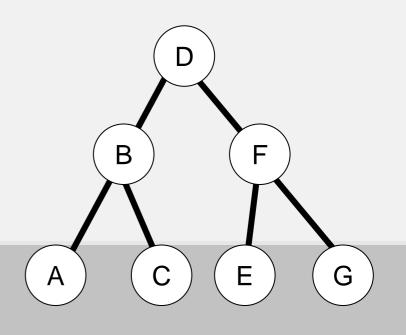
Create an optimal binary search tree

DATA	Probability
Α	0.25
В	0.22
C	0.20
D	0.18
E	0.08
F	0.05
G	0.02



Create an optimal binary search tree

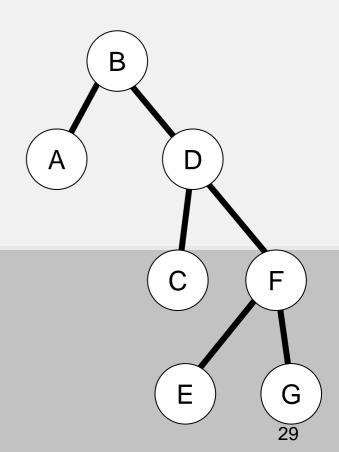
DATA	Probability	TIME
Α	0.25	3
В	0.22	2
С	0.20	3
D	0.18	1
E	0.08	3
F	0.05	2
G	0.02	3



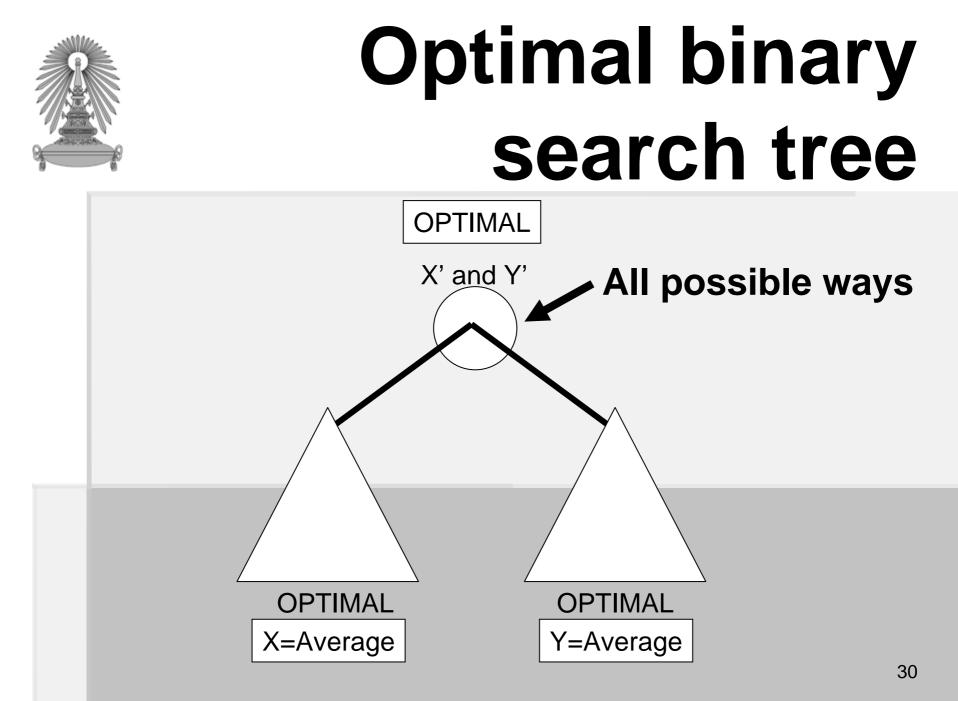


Create an optimal binary search tree

DATA	Probability	ТІМЕ
Α	0.25	2
В	0.22	1
С	0.20	3
D	0.18	2
E	0.08	4
F	0.05	3
G	0.02	4



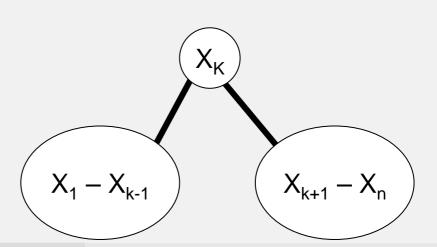
Average-time for searching **1.98**





Create an optimal binary search tree

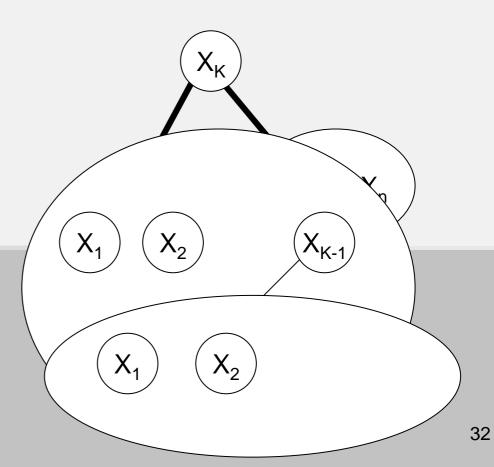
DATA	Probability
X ₁	P ₁
X ₂	P ₂
X ₃	P ₃
X ₄	P ₄
X ₅	P ₅
X ₆	P ₆
X ₇	p ₇





Create an optimal binary search tree

DATA	Probability
X ₁	P ₁
X ₂	P ₂
X ₃	P ₃
X ₄	P ₄
X ₅	P ₅
X ₆	P ₆
X ₇	p ₇





Create an optimal binary search tree

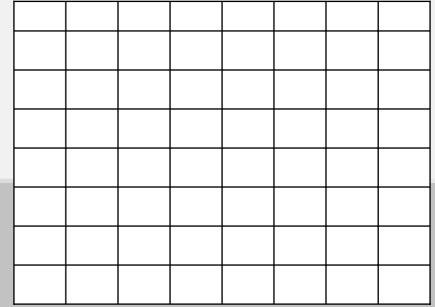
1

2

n

DATA	Probability
X ₁	P ₁
X ₂	P ₂
X ₃	P ₃
X ₄	P ₄
X ₅	P ₅
X ₆	P ₆
X ₇	p ₇

DICTIONARY



2

1



Create an optimal binary search tree

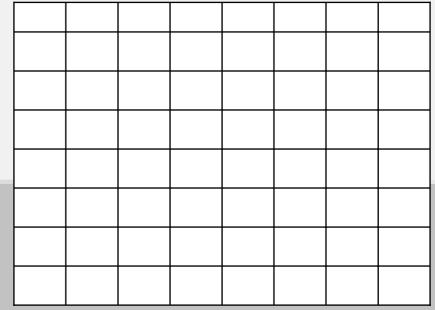
1

2

n

DATA	Probability
X ₁	P ₁
X ₂	P ₂
X ₃	P ₃
X ₄	P ₄
X ₅	P ₅
X ₆	P ₆
X ₇	p ₇

DICTIONARY



2

1

n



Create an optimal binary search tree

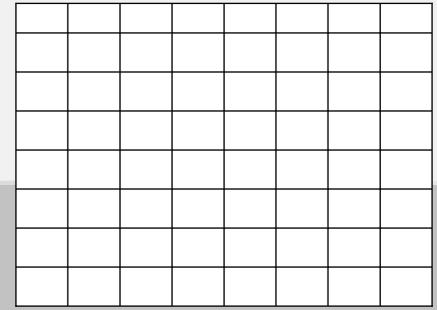
1

2

n

DATA	Probability
X ₁	P ₁
X ₂	P ₂
X ₃	P ₃
X ₄	P ₄
X ₅	P ₅
X ₆	P ₆
X ₇	p ₇

DICTIONARY



2

1

n



Create an optimal binary search tree

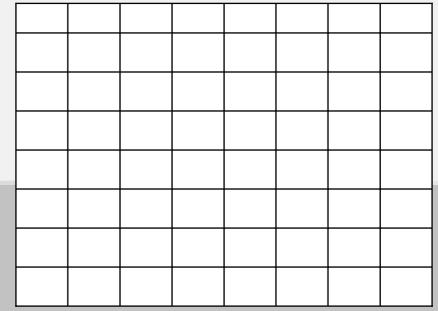
1

2

n

DATA	Probability
X ₁	P ₁
X ₂	P ₂
X ₃	P ₃
X ₄	P ₄
X ₅	P ₅
X ₆	P ₆
X ₇	p ₇

DICTIONARY



2

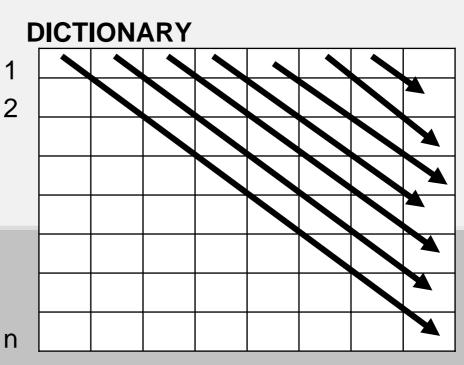
1

n



Create an optimal binary search tree

DATA	Probability
X ₁	P ₁
X ₂	P ₂
X ₃	P ₃
X ₄	P ₄
X ₅	P ₅
X ₆	P ₆
X ₇	p ₇

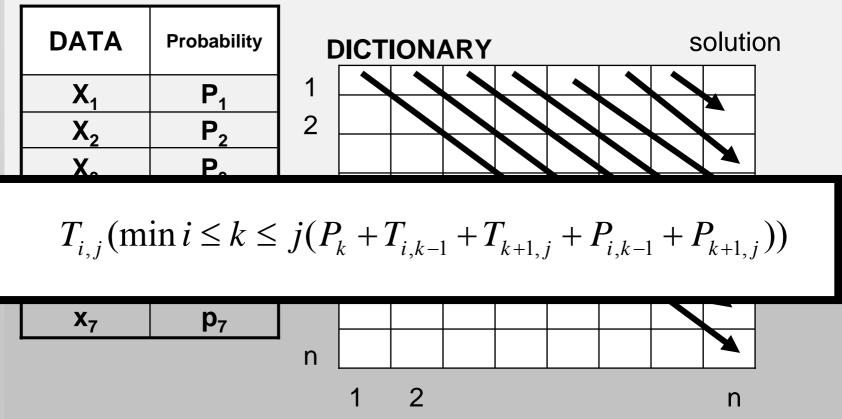


2

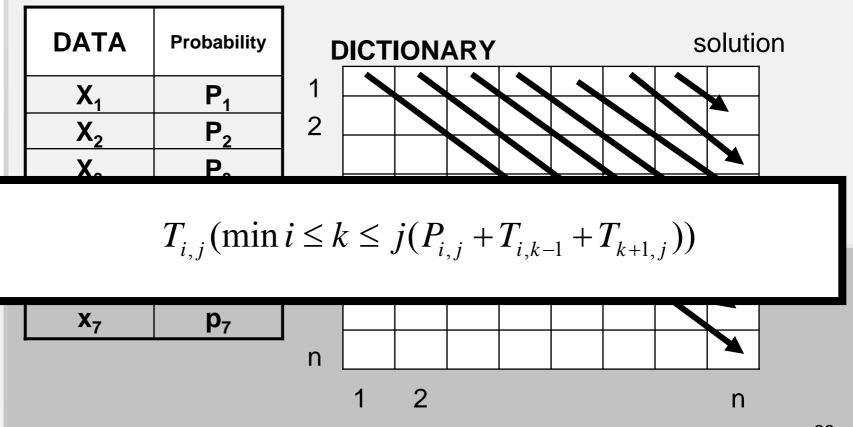
1

n

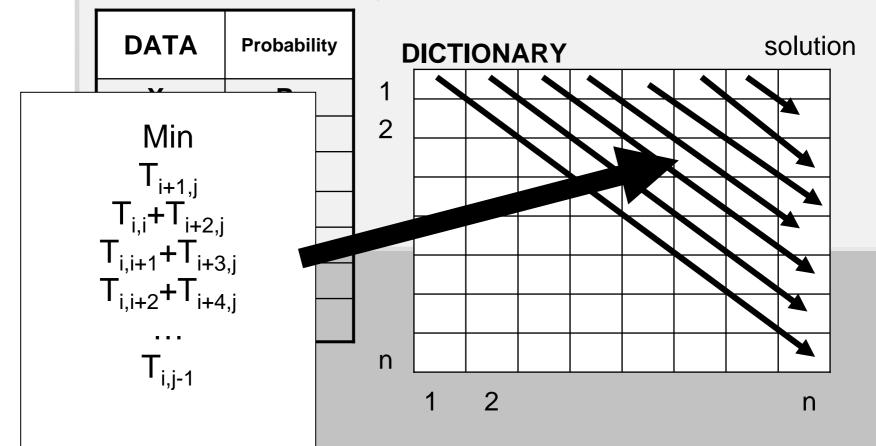






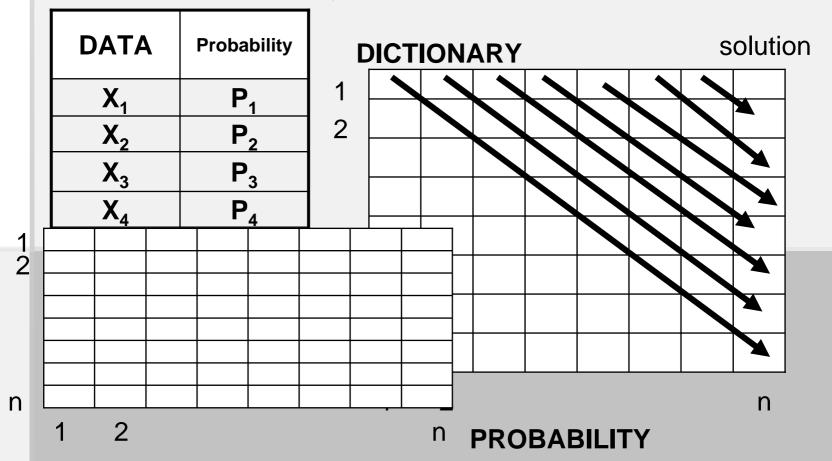








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- S_k : Set of items numbered 1 to *k*.
- Define B[k,w] = best selection from S_k with weight exactly equal to w
- Best subset of S_k with weight exactly *w* is either:
 - - the best subset of S_{k-1} weight w
 - - the best subset of S_{k-1} weight $w-w_k$ plus item k

$$B[k,w] = \begin{cases} B[k-1,w] & \text{if } w_k > w \\ \max\{B[k-1,w], B[k-1,w-w_k] + b_k\} & \text{otherwise} \end{cases}$$



0/1 Knapsack

 Since B[k,w] is defined in terms of B[k-1,*], we can reuse the same array

Algorithm 0-1Knapsack(S, W):

Input: set S of items with benefit b_i and weight w_i ; max. weight W Output: value of best subset with weight $\leq W$ for $w \leftarrow 0$ to W do $B[0,w] \leftarrow 0$ for $k \leftarrow 1$ to n do for $w \leftarrow W$ down to w_k do $B[k,w] \leftarrow \max(B[k-1,w], B[k-1,w-w_k]+b_k)$



0/1 Knapsack

Since B[k,w] is defined in terms of B[k-1,*], we can reuse the same array

Algorithm 0-1Knapsack(S, W):

Input: set *S* of items with benefit b_i and weight w_i ; max. weight *W* **Output:** value of best subset with weight $\leq W$

for $w \leftarrow 0$ to W do

 $B[0,w] \leftarrow 0$
for $k \leftarrow 1$ to n do

Running time: O(*nW*).

for $w \leftarrow W$ downto w_k do

 $B[k,w] \leftarrow \max(B[k-1,w],$

 $B[k-1, w-w_k]+b_k)$



All shortest Floyd-Warshpaths

Given a directed weighted graph G + (V, E) find all shortest paths between any two vertices in G.

- If we already know the all shortest paths whose intermediate vertices belong to the set {1,...,k-1}, how can we find all shortest paths with intermediate vertices {1,...,k}?
- Consider the shortest path p between (i, j), whose intermediate vertices belong to {1,...k}
- If *k* is not an intermediate vertex in *p*, then *p* is the path found in the previous iteration.
- If k is in p, then we can write p as i~> k ~> j, where the intermediate vertices in i~> k and k~> j belong to {1,...,k-1}.

$d_{i,j}(k) = \min(d_{i,j}(k-1), d_{i,k}(k-1) + d_{k,j}(k-1))$

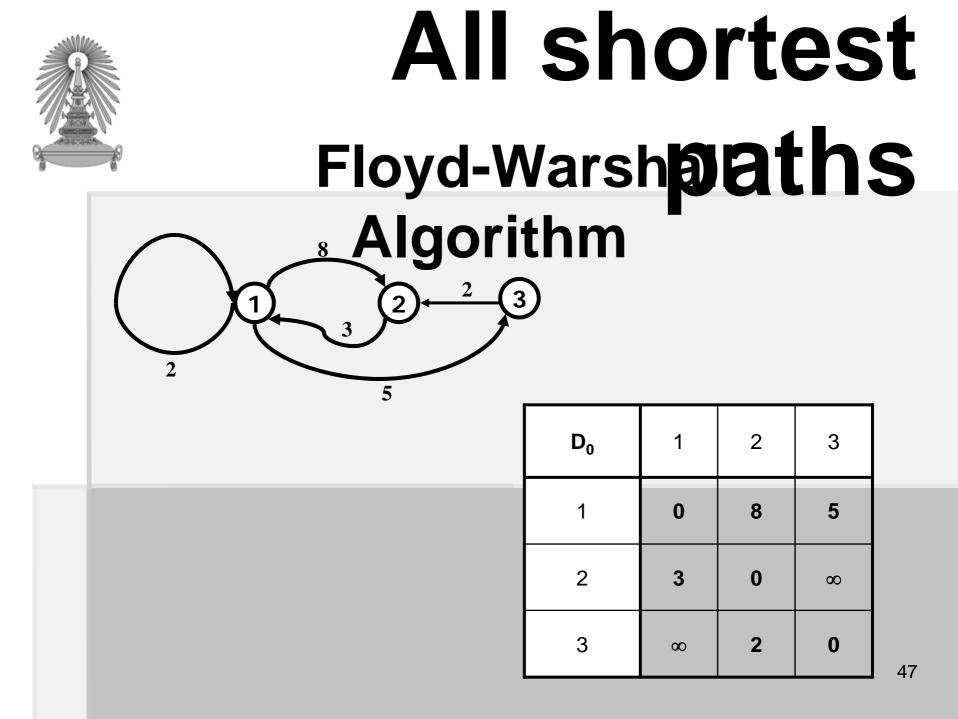


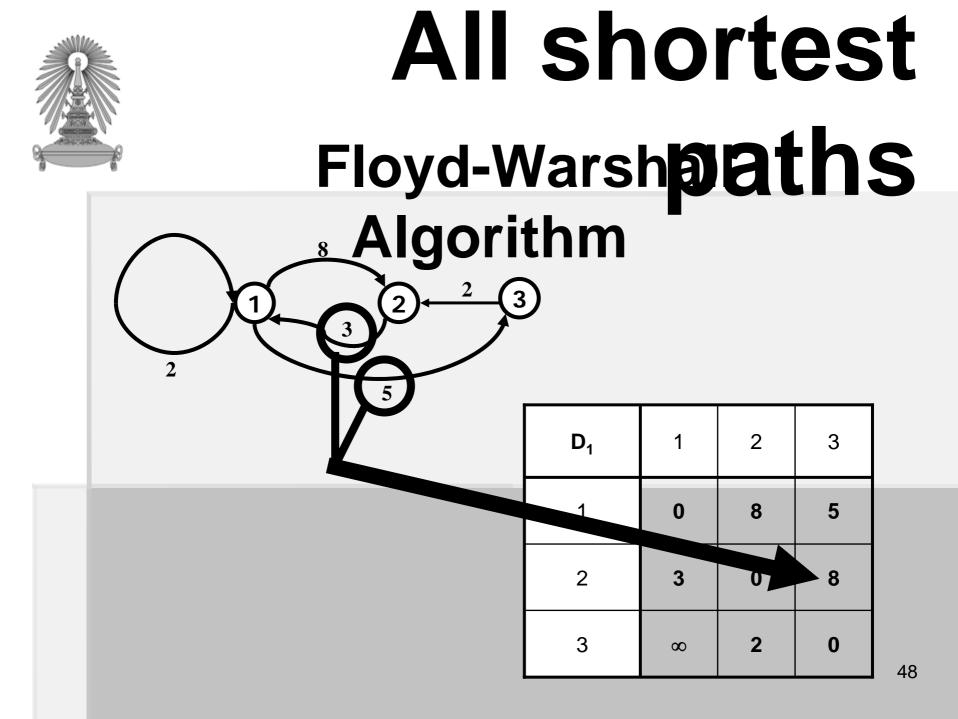
All shortest Floyd-Warshalaths Given a directed weighted graph of the former of the f

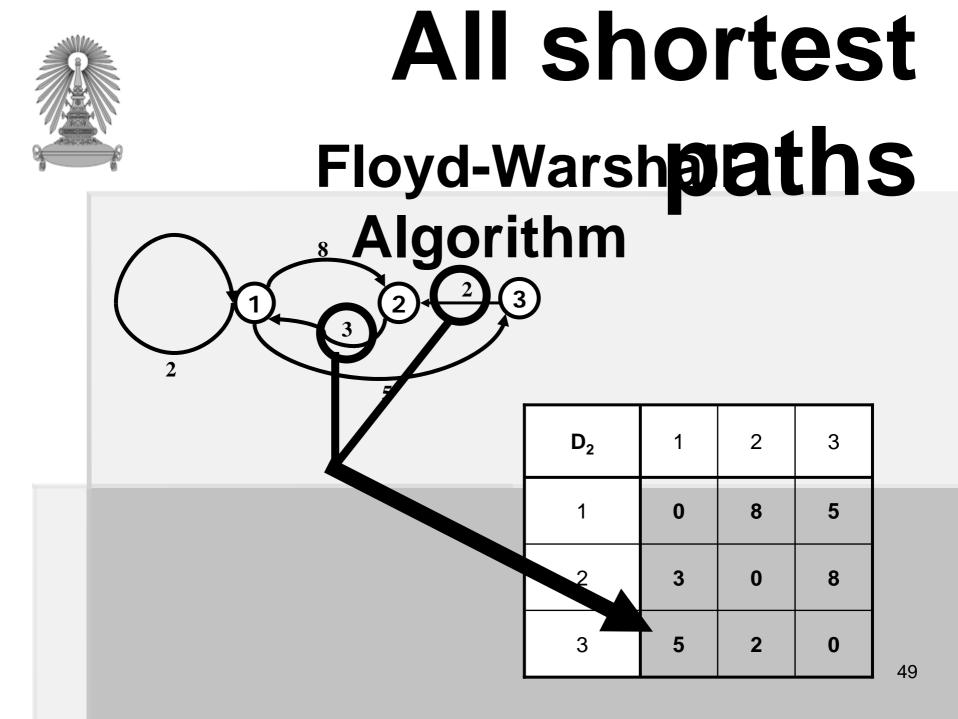
The algorithm:

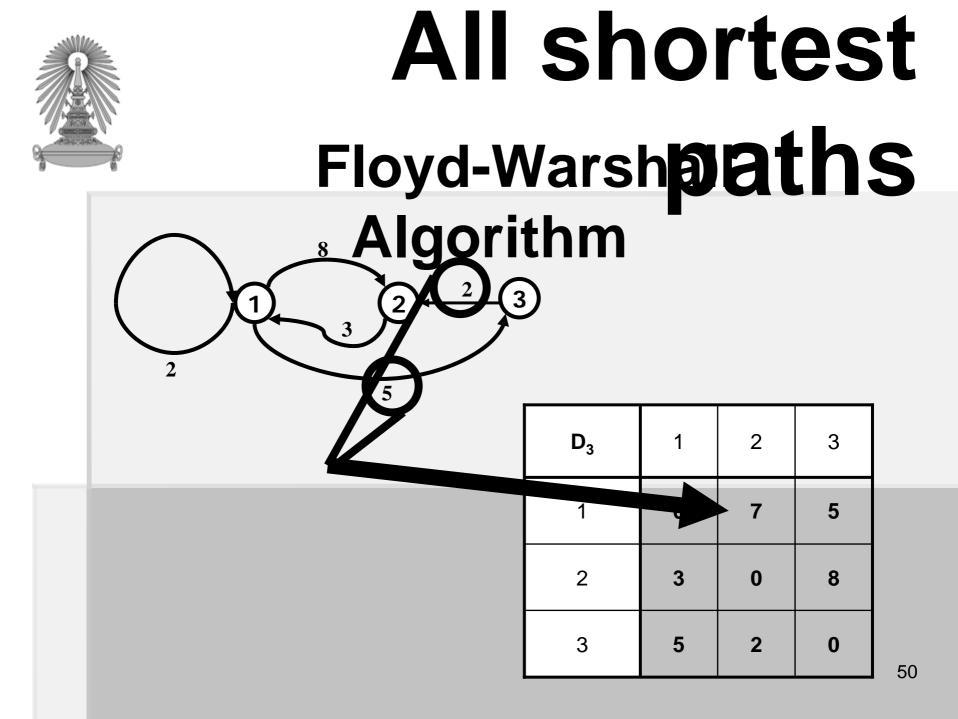
-Initialize:
$$D_{(0)} = W$$

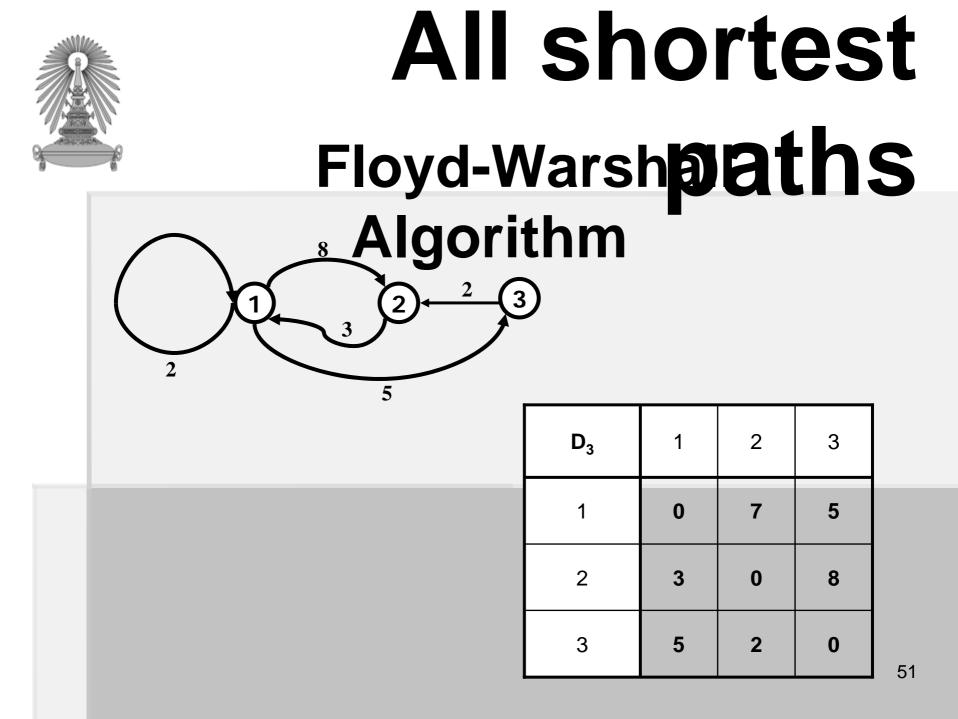
-For $k = 1.../V$ /
 $= O(|V|^3)$
Time complexity = $O(|V|^3)$
 $= I.../V$ /
 $> d_{i,j}(k) = min(d_{i,j}(k-1), d_{i,k}(k-1)+d_{k,j}(k-1)$













Given two sequences

- $\mathbf{X} = \mathbf{ABCB}$
- Y = BDCAB



Find the longest common subsequence of two sequences

- $\mathbf{X} = \mathbf{ABCB}$
- $\mathbf{Y} = \mathbf{BDCAB}$

Brute force algorithm would compare each subsequence of X with the symbols in Y.

If |X| = m, |Y| = n, then there are 2^m subsequences of x; we must compare each with Y (n comparisons).

So the running time of the brute-force algorithm is O(n 2^m).

Notice that the LCS problem has *optimal substructure*: solutions of subproblems are parts of the final solution.



Find the longest common subsequence of two sequences

• $\mathbf{X} = \mathbf{ABCB}$

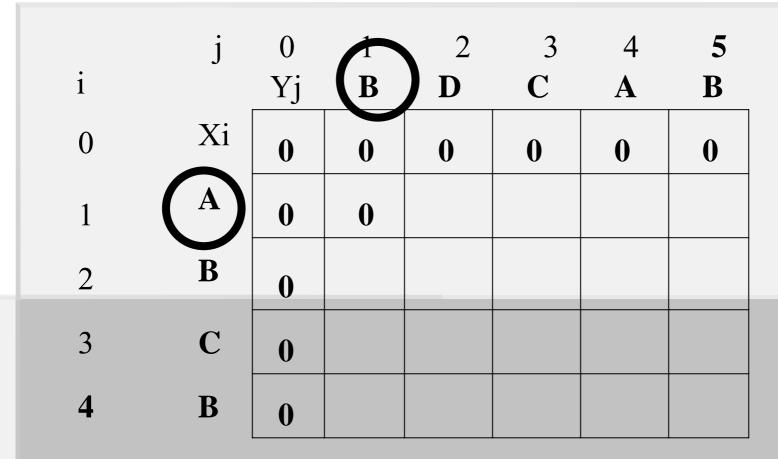
• Y = BDCAB

Define X_i , Y_j to be the prefixes of X and Y of length i and j respectively Define c[i,j] to be the length of LCS of X_i and Y_j

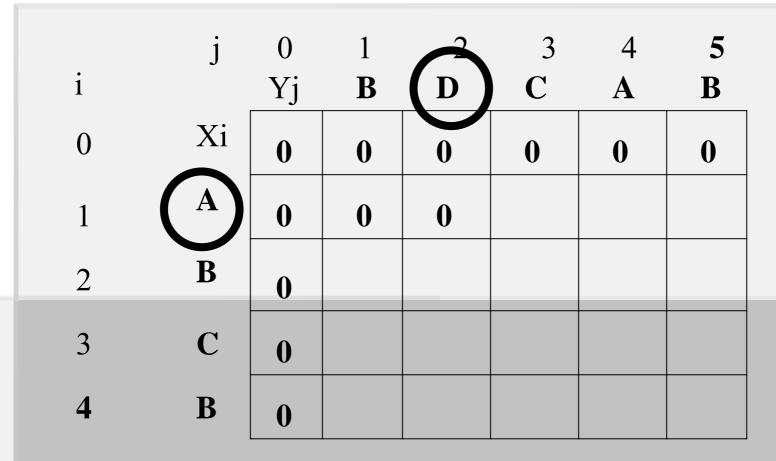
Then the length of LCS of X and Y will be c[m,n]

$$c[i, j] = \begin{cases} c[i-1, j-1]+1 & \text{if } x[i] = y[j], \\ \max(c[i, j-1], c[i-1, j]) & \text{otherwise} \end{cases}$$

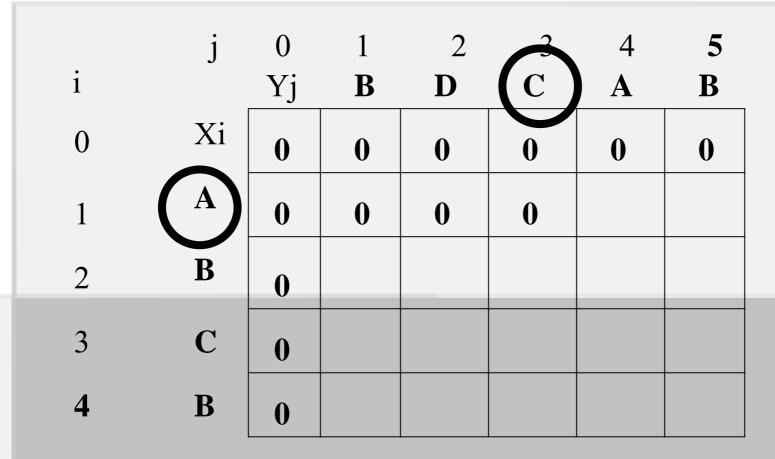




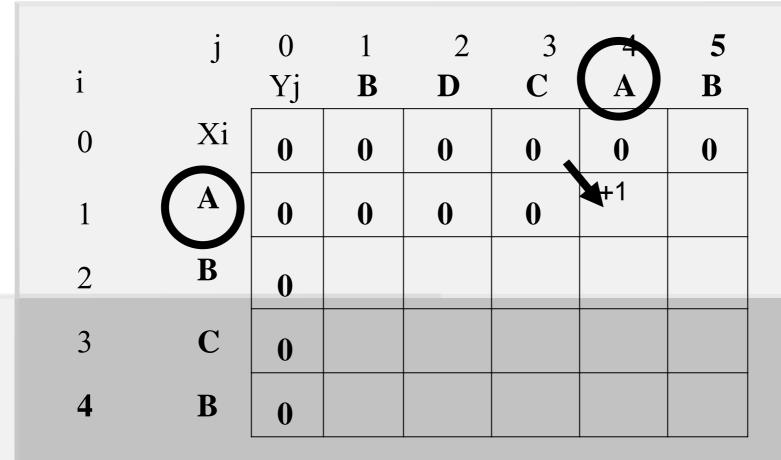




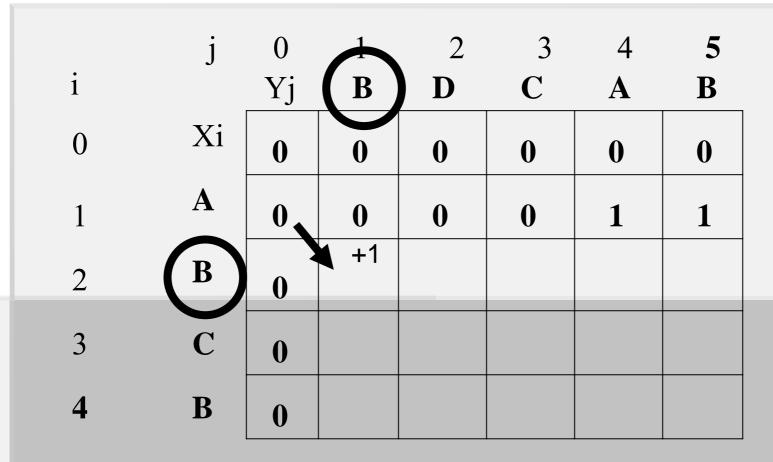




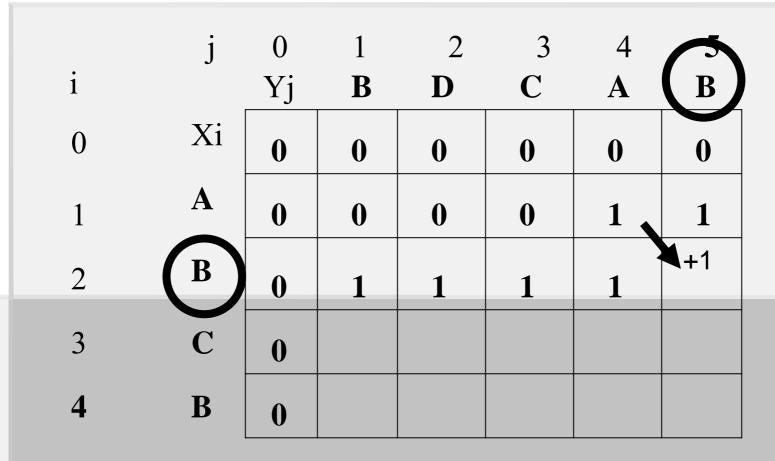




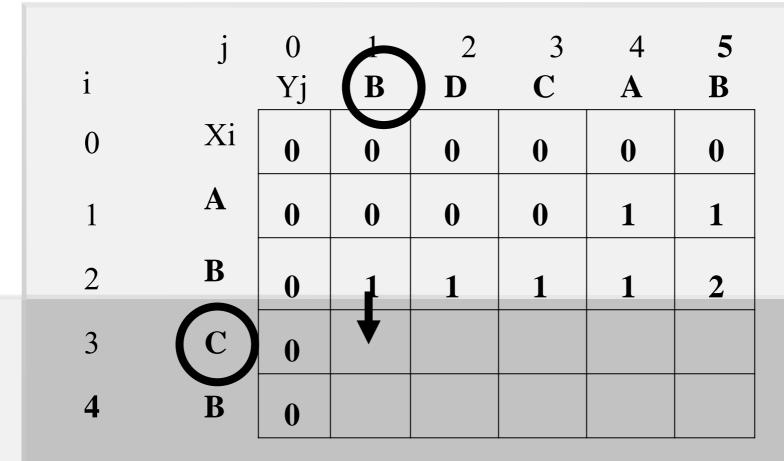




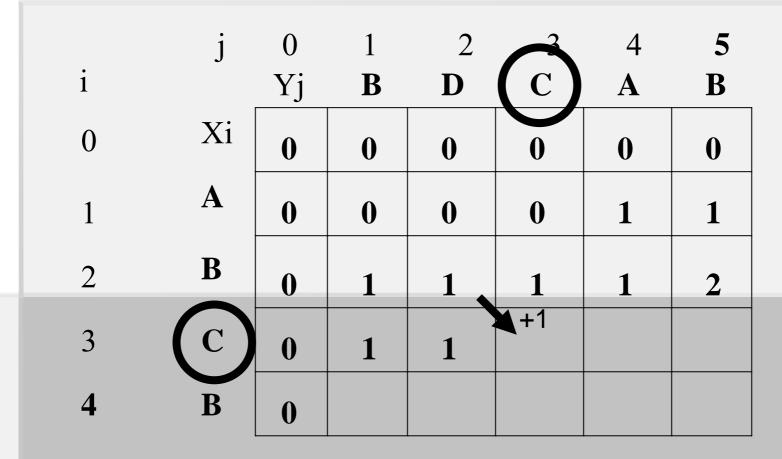




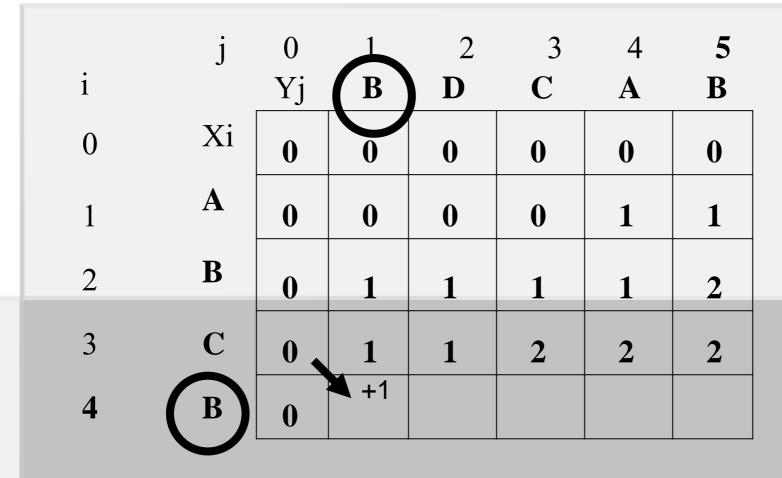




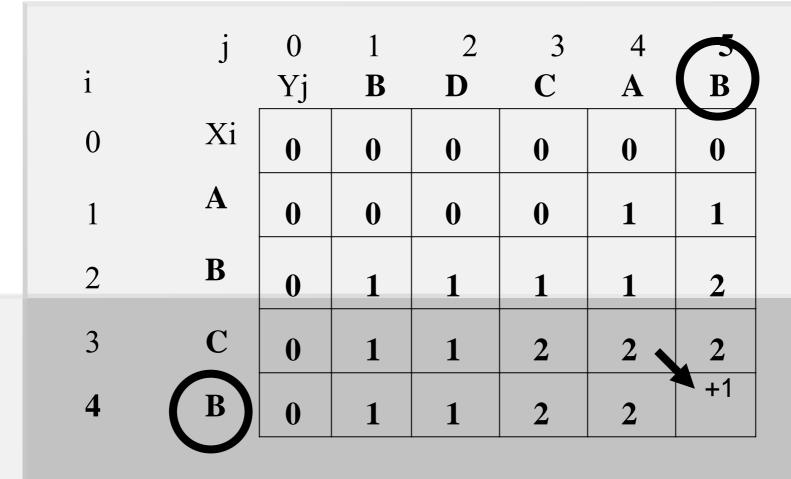




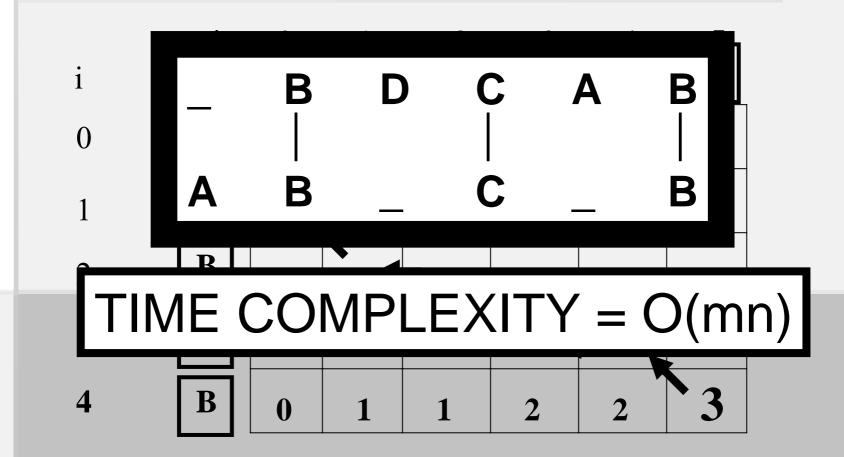














Natural Natural Ianguage Given a sentence (sequence of words)

John called Mary from Denver.

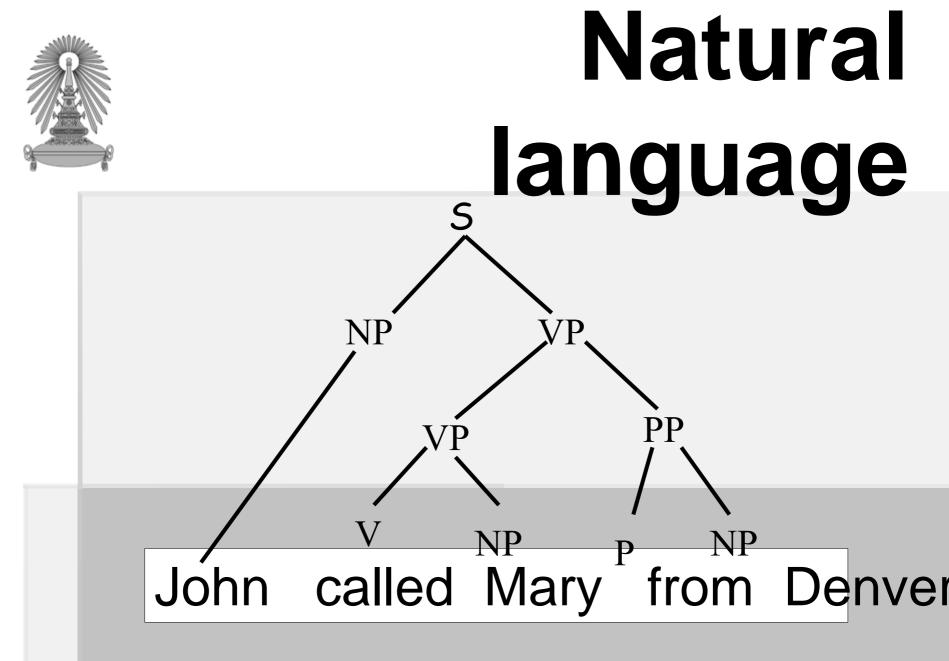
Find a grammar tree matched to X.

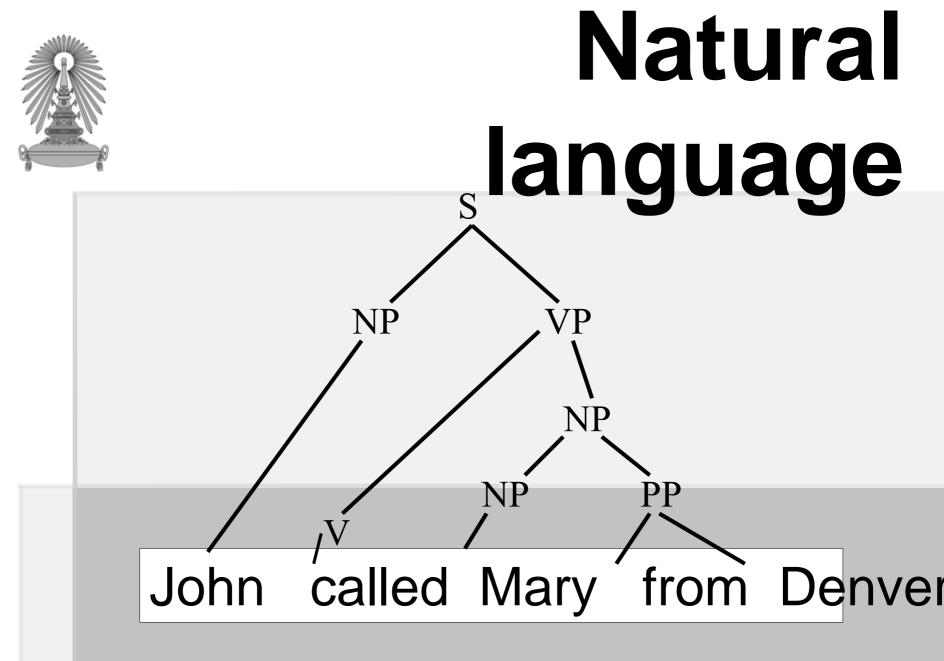
Given GRAMMAR $S \rightarrow NP VP$	John	NP	
$VP \rightarrow V NP$	called		V
$NP \rightarrow NP PP$	Mary	NP	
$VP \rightarrow VP PP$	from	P	
$PP \rightarrow P NP$	Denver	NP	66

Natural language

John called Mary from Denver.

Given GRAMMAR John NP $S \rightarrow NP VP$ called \mathbf{V} $VP \rightarrow V NP$ Mary NP $NP \rightarrow NP PP$ from Ρ $VP \rightarrow VP PP$ $PP \rightarrow P NP$ Denver NP





		Natura			al
			ang	Juag	e
					-
					_
John	called	Mary	from	Denver	

	N			atura
			ang	uag
			P	Denver
		NP	from	
	V	Mary		
NP	called			
John				

	Natu			atura
			ang	Juage
			P	Denver
		NP	from	
X	V	Mary		
NP	called			
John				

			Na	atural
			ang	juage
			P	Denver
	VP	→ NP	from	
X	V	Mary		
NP	called			
John				

				Na	atura	
				ang	Juag	e
			X	Р	Denver	-
		VP	NP	from		
	x	V	Mary			
Ē	NP	called				
•	John					

			Na	atura
			ang	Juage
		X	↓ P	Denver
	VP	NP	from	
X	V	Mary		
NP	called			
John				

2			Na	atura
			ang	Juage
		X	P	Denver
S	VP	NP	from	
	V	Mary		
NP	called			
John				

			Na	atura
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	X	X	P	Denver
S	VP	NP	from	
X	V	Mary		
NP	called			
John				

			Na	atura
		NP —	lang	Juage
	X		P	Denver
S	VP	NP	from	
X	V	Mary		
NP	called			
John				

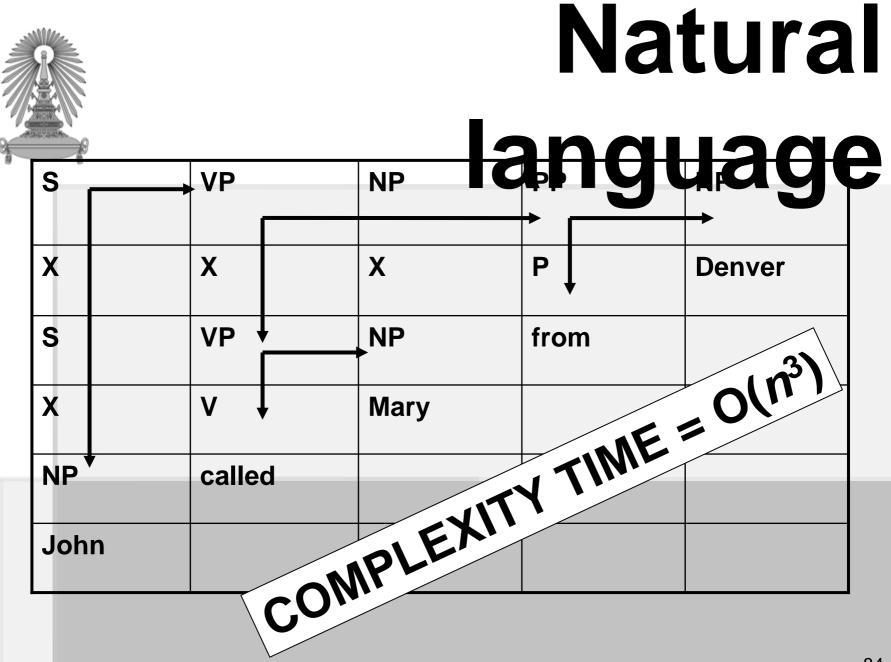
			Na	atur
		NP	lang	Juag
x	X	X	P	Denver
S	VP	NP	from	
X	V	Mary		
NP	called			
John				

			Na	atura	
	VP	NP	lang	Juage	9
X	X	X	P	Denver	
S	VP	NP	from		
X	V	Mary			
NP	called				
John					

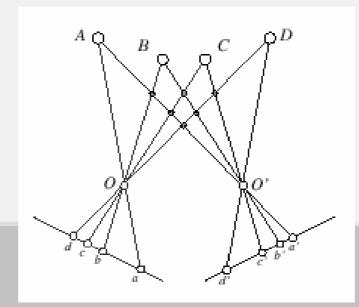
			Na	atura
	VP	NP	ang	Juag
x	X	X	P	Denver
S	VP	NP	from	
x	V	Mary		
NP	called			
John				

2			Na	atura	
	VP ₁ VP ₂	NP	ang	Juag	e
X	X	X	P	Denver	
S	VP	NP	from		
X	V	Mary			
NP	called				
John					

			Na	atura	
S	VP ₁	NP	ang	Juage	9
X	VP2 X	X	P	Denver	
S	VP	NP	from		
X	V	Mary			
NP	called				
John					

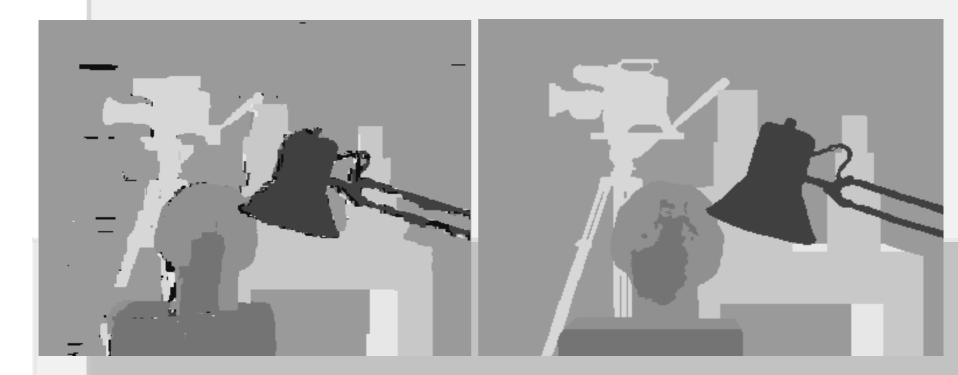


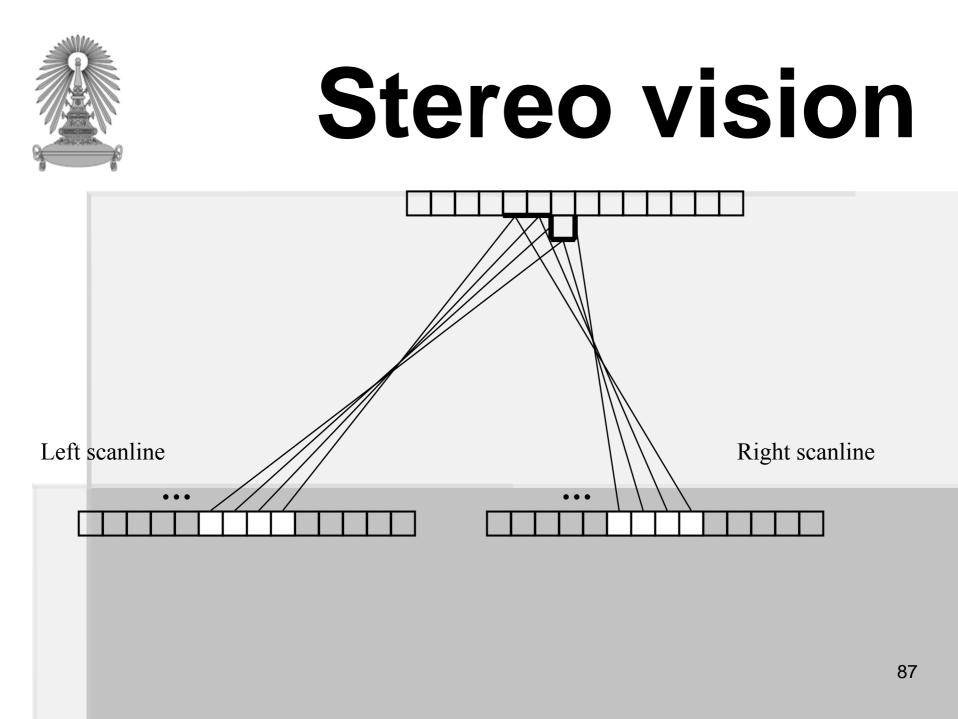


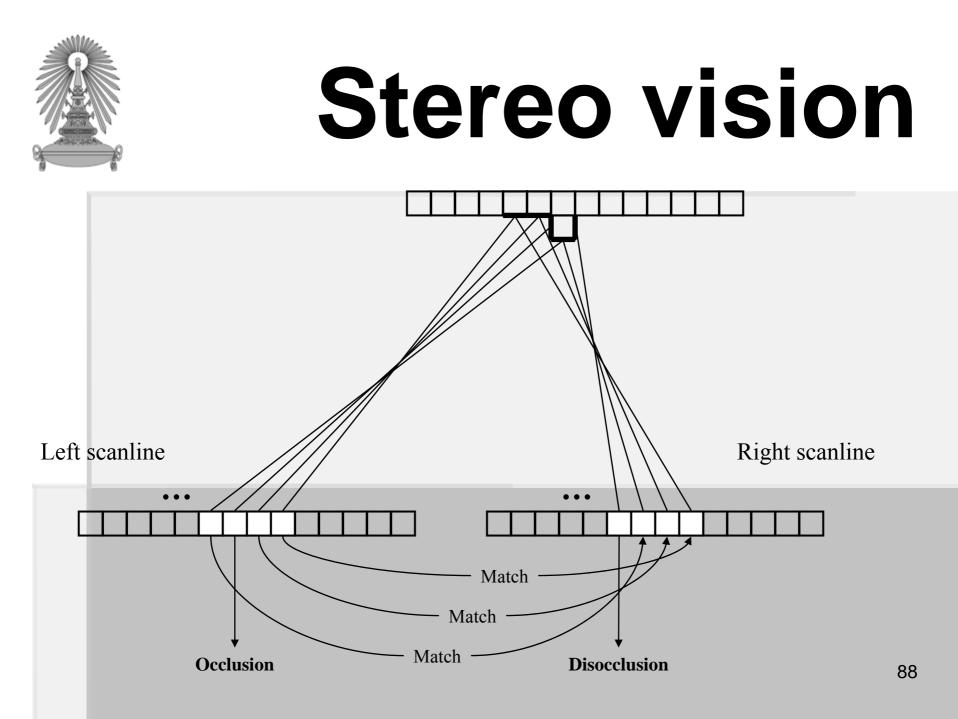


Ordering constraint...

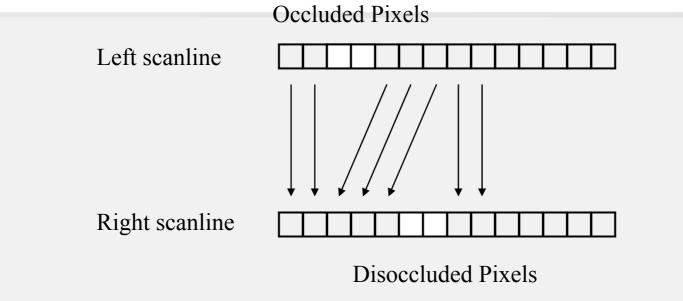








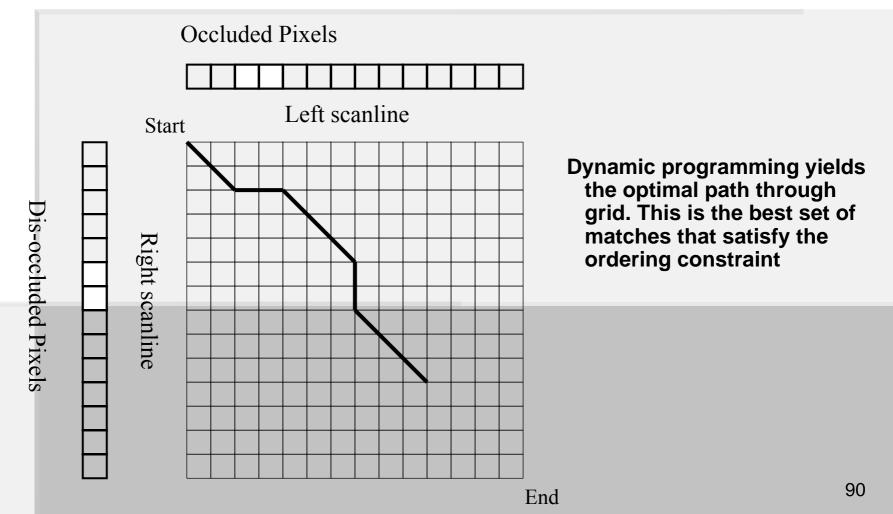




Three cases:

- Sequential add cost of match (small if intensities agree)
- Occluded add cost of no match (large cost)
- Disoccluded add cost of no match (large cost)



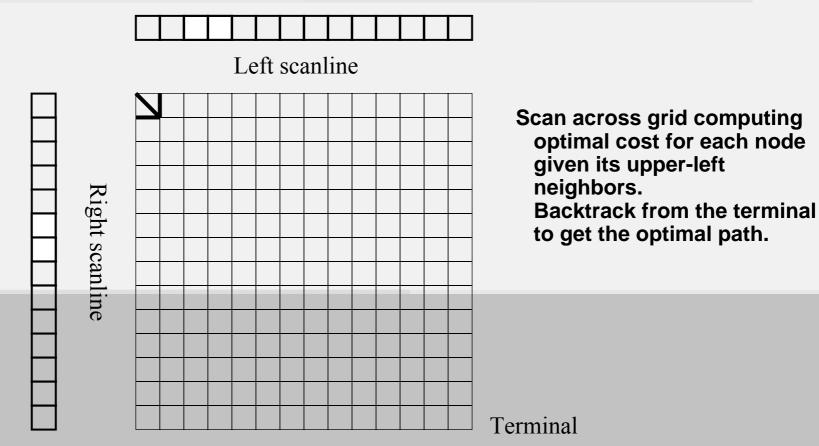




Dis-occluded Pixels

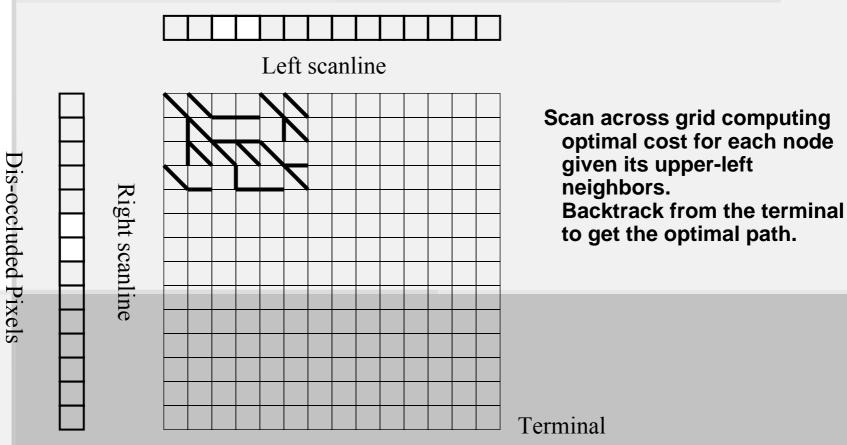
Stereo vision

Occluded Pixels





Occluded Pixels

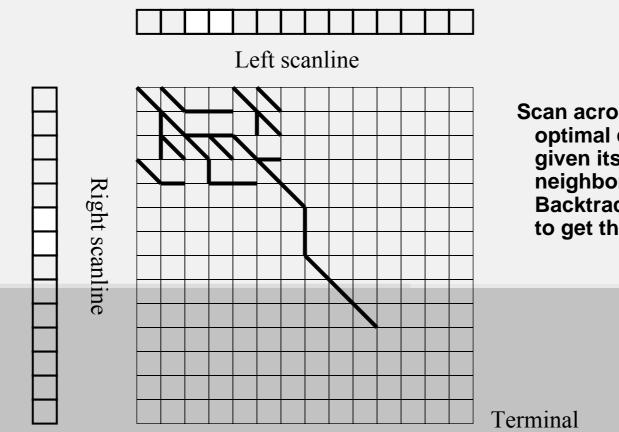




Dis-occluded Pixels

Stereo vision

Occluded Pixels

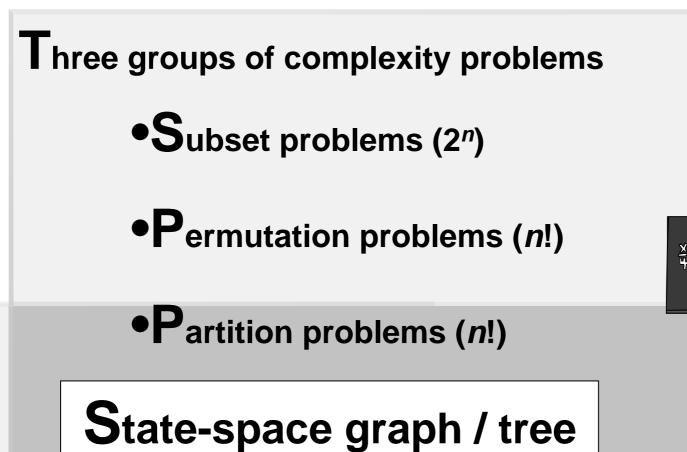


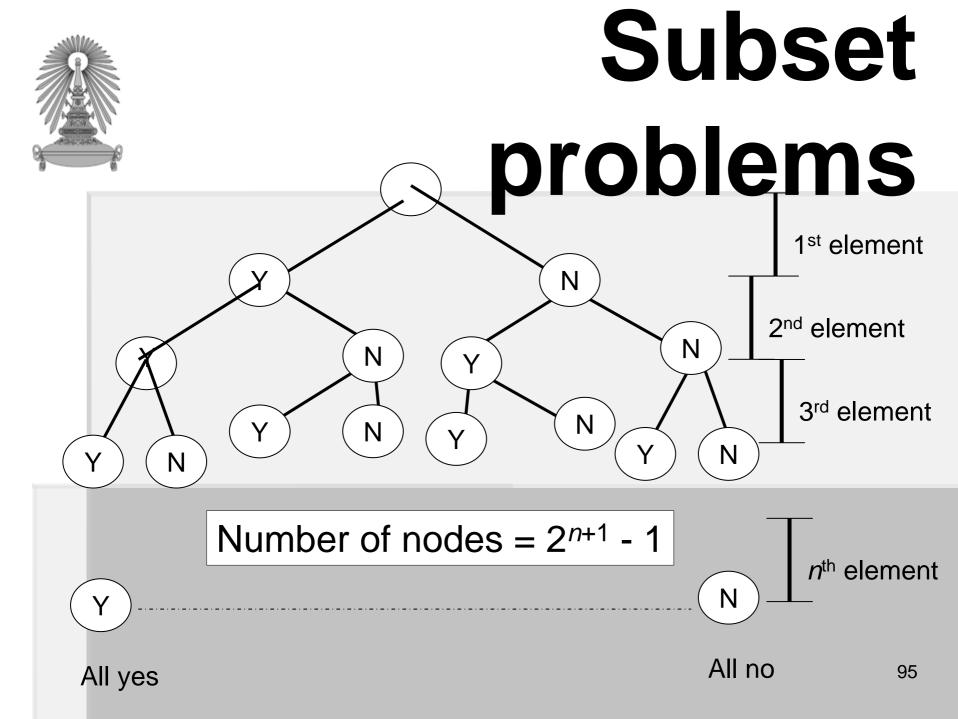
Scan across grid computing optimal cost for each node given its upper-left neighbors.

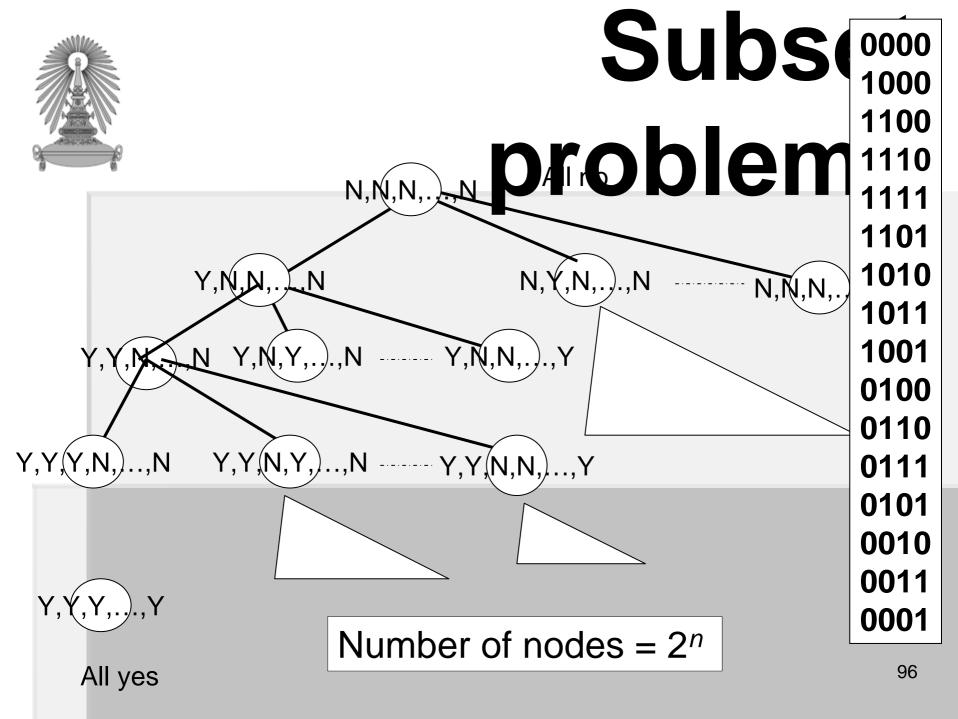
Backtrack from the terminal to get the optimal path.

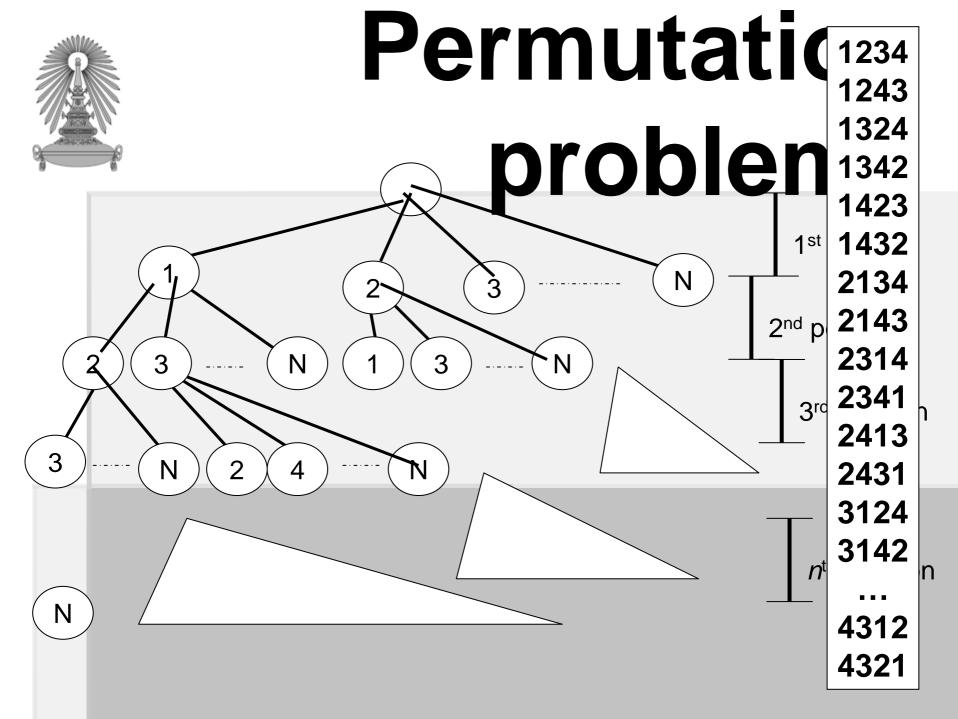


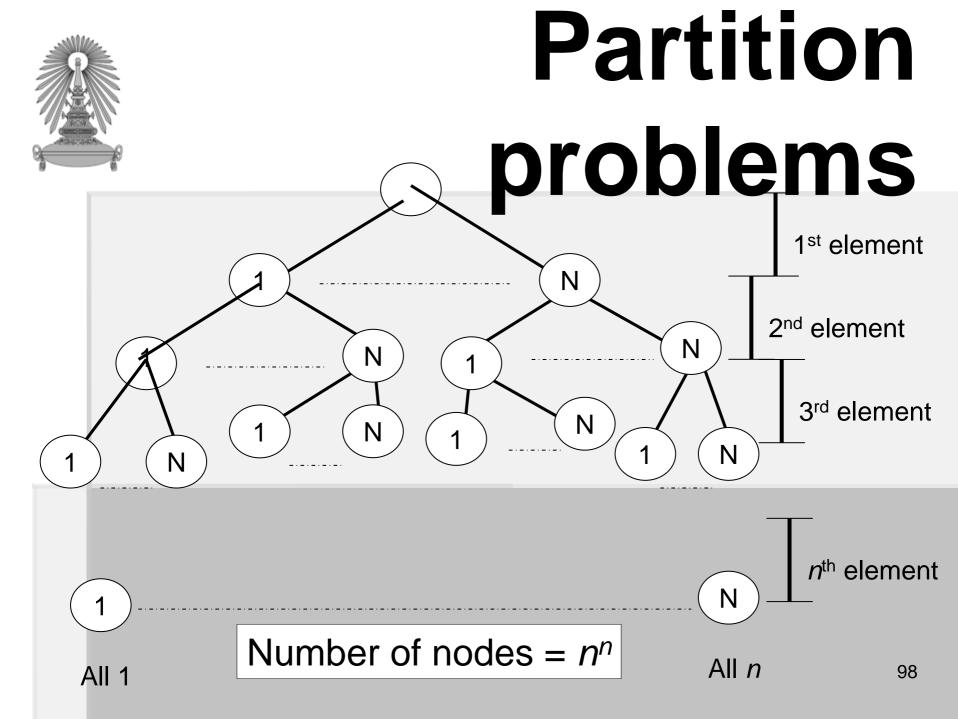
Problems













Traversal

Three possible ways

Depth-first technique

- Breadth-first technique
- Best-first technique



Back tracking

Technique

- Depth-first technique
- Keep track and return back when it cannot be branched.



Branch & bound

	1	2	3	4
A	10	7	13	15
В	12	5	16	12
С	14	9	14	20
D	11	7	14	13