Evolutionary Computation and Machine Intelligence

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1

What is Evolutionary Computation What is Machine Intelligence How EC works Learning Robotics Examples Future research EC is a probabilistic search procedure to obtain solutions starting from a set of candidate solutions, using improving operators to "evolve" solutions. Improving operators are inspired by natural evolution.

Survival of the fittest.

The objective function depends on the problem.

EC is not a random search.

GA pseudo code

```
initialise population P
while not terminate
  evaluate P by fitness function
  P' = selection.recombination.mutation of P
  P = P'
```

terminating conditions:

- 1 found satisfactory solutions
- 2 waiting too long

Simple Genetic Algorithm

represent a solution by a binary string {0,1}* selection:

chance to be selected is proportional to its fitness recombination

single point crossover

recombination

select a cut point cut two parents, exchange parts



mutation

single bit flip
111111 --> 111011 flip at bit 4

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6

Evolution Strategy

represent solutions with real numbers

GA compare to other methods

"indirect" -- setting derivatives to 0 "direct" -- hill climber enumerative – search them all random – just keep trying simulated annealing – single-point method Tabu search

What problem GA is good for?

Highly multimodal functions Discrete or discontinuous functions High-dimensionality functions, including many combinatorial ones Nonlinear dependencies on parameters (interactions among parameters) -- "epistasis" makes it hard for others Often used for approximating solutions to NPcomplete combinatorial problems

What is Machine Intelligence?

... Exactly what the computer provides is the ability not to be rigid and unthinking but, rather, to behave conditionally. That is what it means to apply knowledge to action: It means to let the action taken reflect knowledge of the situation, to be sometimes this way, sometimes that, as appropriate....

Allen Newell

What is Machine Intelligence?

"It is the science and engineering of making intelligent machines, especially intelligent computer programs. It is related to the similar task of using computers to understand human intelligence, but AI does not have to confine itself to methods that are biologically observable. "

What is intelligence?

"Intelligence is the computational part of the ability to achieve goals in the world. Varying kinds and degrees of intelligence occur in people, many animals and some machines. "

John McCarthy

Creation of machines that can "think"

perception reasoning planning acting (manipulation)

machine vision

Learning

machine learning building hypothesis from positive and negative examples.

artificial neuron networks building approximate function mapping from inputs to outputs: classification, memorisation etc.

Robotics

integrate sensing and action to achieve some tasks

Applications of Machine intelligence

game playing speech recognition understanding natural language computer vision expert systems

agent-based systems autonomous systems collaborative robots (perhaps with human) adaptive systems assistant to human (such as secretary) EC + MI

robot programming evolutionary robotics

Examples

evolving robot arm programs evolving programs for biped robots learning automata SET index forecasting







T = { s+, s-, e+, e-, w+, w-, HIT?, SEE?, INC?, DEC?, OUT?}. F = { IF-AND, IF-OR, IF-NOT}.

(IF-AND w+ w+ e+ (IF-AND (IF-NOT (IF-NOT OUT? s- w+) (IF-AND e+ s- e-(IF-OR (IF-NOT w+ s+ e+) s+ e- e-)) (IF-OR (IF-NOT SEE? w- e-) w+ e+ e+)) w- (IF-OR SEE? (IF-OR e- (IF-OR (IF-OR HIT? e+ s+ e-) INC? w- e-) s+ w+) (IF-AND (IF-NOT w- e- e-) w- w- w+) s-) e+)))



Fig. 3. Biped construction



Fig. 5. Simulation + real world

Learning Automata

The problem of modeling the environment, that is, assuming a robot can sense and act in the world, models the world such that we can predict the consequence of the robot's action.

We conduct experiments on generating Finite State Machine from the observed sensing/action sequences.

Figure 1. Mimicking a FSM by observing its partial input/output sequences



Table 1. Description of circuits in the experiment

| Circuit | # of input bits | # of states | | lower bound length | | upper bound length |
|---------------------|-----------------------|-------------|-------|-----------------------|-----------|--------------------------|
| | | Moor e | Mealy | Moor e | Meal v | |
| Frequency Divider | 0 | 8 | 8 | 22 | 22 | 55 |
| Odd Parity Detector | 1 | 2 | 2 | 9 | 9 | 163 |
| Modulo-5 Detector | 1 | 6 | 5 | 45 | 35 | 163 |
| Serial Adder | 2 | 4 | 2 | 70 | 25 | 451 |



Figure 2. GAL structure used in the experiment



In an experiment with the stock exchange prediction, all daily data were obtained from two sources: the data of Thai stock index and Minimum Loan Rate from bank of Thailand and gold price data from Gold Trader Association. The series that used in the experiment started from January 2003 - December 2004, the data are 491 days. The data are divided into two groups: 420 days for training and 71 days for testing.



How far is AI from reaching human-level intelligence? When will it happen?

"A few people think that human-level intelligence can be achieved by writing large numbers of programs of the kind people are now writing and assembling vast knowledge basis of facts in the languages now used for expressing knowledge.

However, most AI researchers believe that new fundamental ideas are required, and therefore it cannot be predicted when human level intelligence will be achieved. "

John McCarthy

Future Research

My website http://www.cp.eng.chula.ac.th/faculty/pjw/

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