

An Introduction to Support Vector Machines and Multiclass Classification

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Outline

- Introduction to Support Vector Machines (SVMs)
- Maximum Margin Hyperplane
- Linear SVMs
- Non-Linear SVMs
- Feature Spaces and Kernels
- Multiclass Support Vector Machines

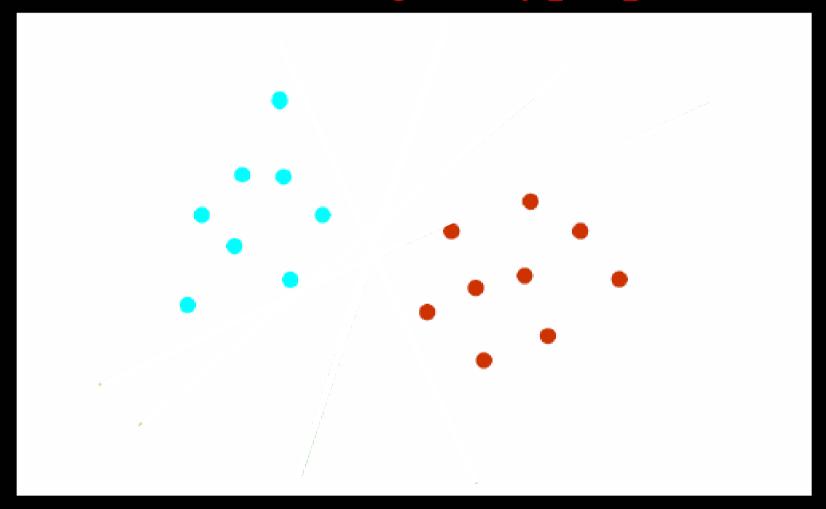
Introduction to SVMs

- Problem:
 - Find a hyperplane that correctly classifies data points from two different classes.
- Solutions: Perceptron, Neural Networks
- SVM constructs an optimal hyperplane that separates the data points of two classes as far as possible [Cortes and Vapnik, 1995].
- Issues: Linear separable, Feature space, Multiclass classification

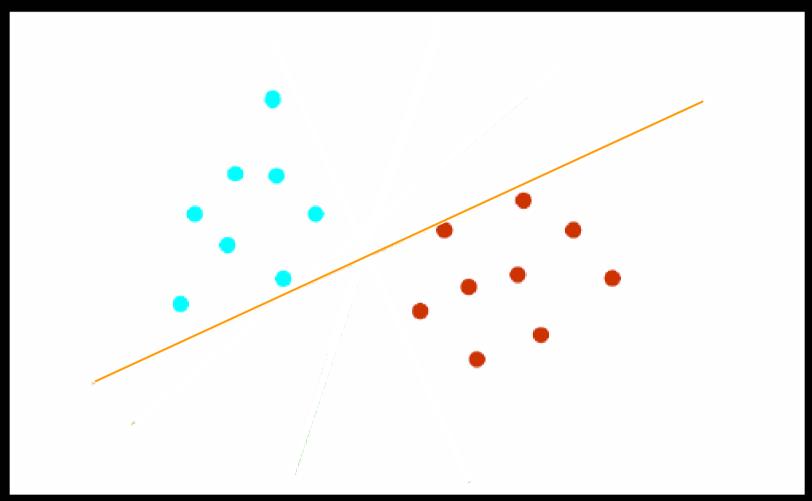
Classification of Fat Child

No	Height (cm.)	Weight	Fat / Not fat	No.	Height	Weight	Fat / Not fat
	(6111.)	(kg.)			(cm.)	(kg.)	
1	100.0	20.0	-1	10	104.9	22.0	-1
2	100.0	26.0	1	11	105.2	20.0	-1
3	100.0	30.4	1	12	105.6	34.4	1
4	100.0	32.4	1	13	107.2	32.4	1
5	101.6	27.0	1	14	109.9	34.9	1
6	101.6	32.0	1	15	111.0	25.4	-1
7	102.0	21.0	-1	16	114.2	23.5	-1
8	103.6	29.6	1	17	115.5	36.3	1
9	104.4	30.4	1	18	117.8	26.9	-1

Maximum Margin Hyperplane

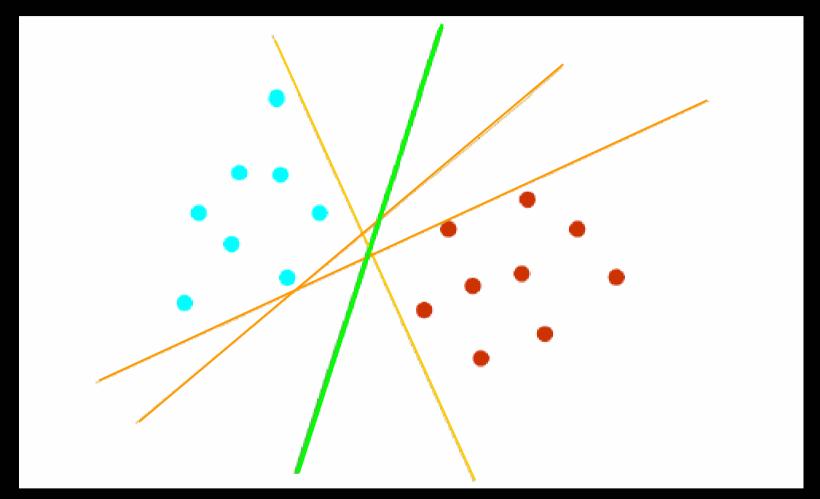


Maximum Margin Hyperplane



• A Yellow hyperplane with small margin.

Maximum Margin Hyperplane



- Yellow hyperplanes with small margin.
- A Green hyperplanes with large margin.
- A better generalization is expected from the green hyperplane.

Linear SVMs

Given a training data set

$$(\mathbf{x}_1, \mathbf{y}_1), \dots, (\mathbf{x}_{\ell}, \mathbf{y}_{\ell}) \in \mathbf{R}^{N} \times \{\pm 1\},$$

Find $f(\mathbf{x})$ such that $f(\mathbf{x}_i) = \mathbf{y}_i$ for all $i=1,\dots,\ell$.

Consider a hyperplane

$$(\mathbf{w} \cdot \mathbf{x}) + \mathbf{b} = 0, \quad \mathbf{w} \in \mathbf{R}^{N}, \, \mathbf{b} \in \mathbf{R},$$

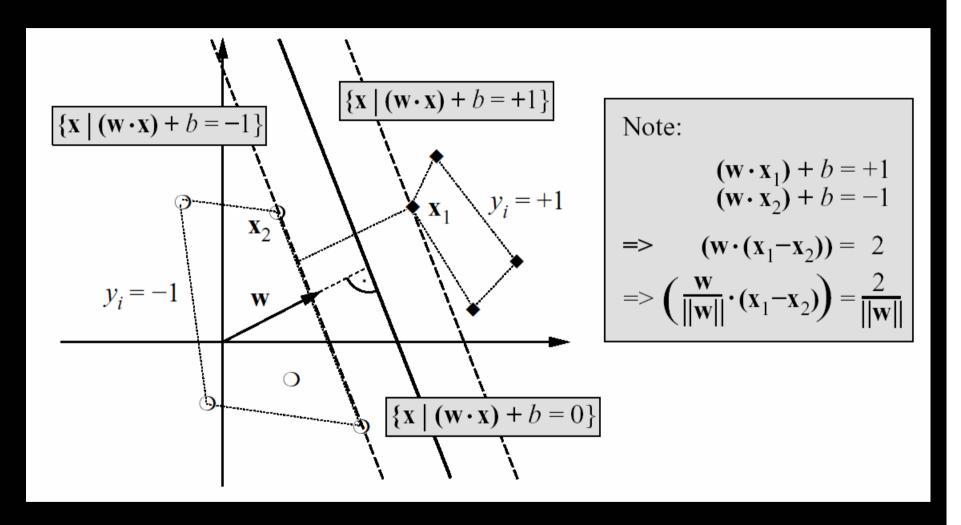
• If we additionally require

$$\min_{i=1,...,\ell} |(\mathbf{w} \cdot \mathbf{x}_i) + \mathbf{b}| = 1,$$

w and b be such that the point closest to the hyperplane has a distance of $1/||\mathbf{w}||$

• Therefore,
$$(\mathbf{w} \cdot \mathbf{x}_i) + b \ge +1$$
 if $y_i = +1$
 $(\mathbf{w} \cdot \mathbf{x}_i) + b \le -1$ if $y_i = -1$,
or $y_i[(\mathbf{w} \cdot \mathbf{x}_i) + b] \ge +1$, $\forall i$

Maximum Margin



• Therefore, we want to maximize 2/||w||, or minimize ||w||/2

Solving SVMs by Quadratic Programming

- Minimize $\frac{1}{2} \|\mathbf{w}\|^2$ subject to $y_i[(\mathbf{w} \cdot \mathbf{x}_i) + b] \ge +1$, for i=1,...,l.
- This constrained optimization problem is dealt with by introducing Lagrange multipliers $\alpha_i \ge 0$ and a Lagrangian

$$L(\mathbf{w},b,\alpha) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^{\ell} \alpha_i ((\mathbf{y}_i((\mathbf{w} \cdot \mathbf{x}_i) + \mathbf{b})))$$

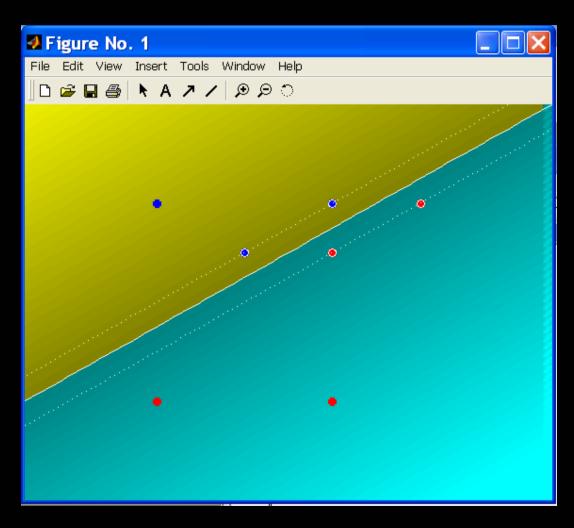
• The solution is

$$\sum_{i=1}^{\ell} \alpha_i y_i = 0 \quad \text{and} \quad w = \sum_{i=1}^{\ell} \alpha_i y_i \mathbf{x}_i$$

- The solution vector thus has an expansion in terms of a subset of the training data, namely those patterns whose a is non-zero, called *support vectors*.
- The hyperplane decision function can be written as

$$f(\mathbf{x}) = \operatorname{sgn}(\sum_{i=1}^{\ell} y_i \alpha_i \cdot (\mathbf{x} \cdot \mathbf{x}_i) + b)$$

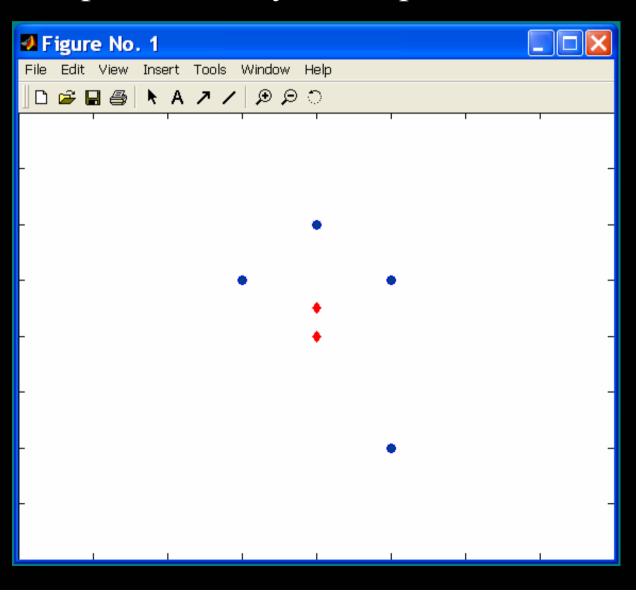
An Example of Linearly Separable Functions



• No. of support vectors = 4

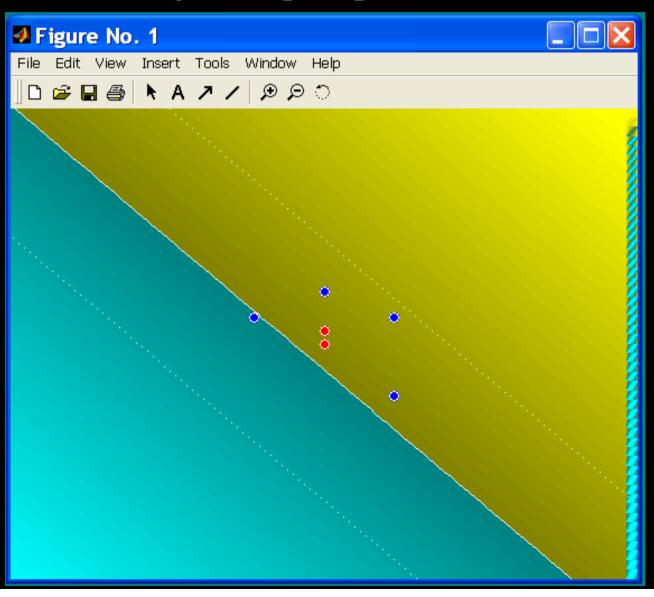
An Example of Linearly Non-Separable Functions

• An example of linearly non-separable functions



An Example of Linearly Non-Separable Functions

• In case of using the input space



Feature Spaces

- For linearly non-separable function, it is very likely that a linear separator (hyperplane) can be constructed in higher dimensional space.
- Suppose we map the data points in the input space Rⁿ into some feature space of higher dimension, R^m using function Φ

$$\Phi: \mathbf{R}^{\mathbf{n}} \to \mathbf{R}^{\mathbf{m}}$$

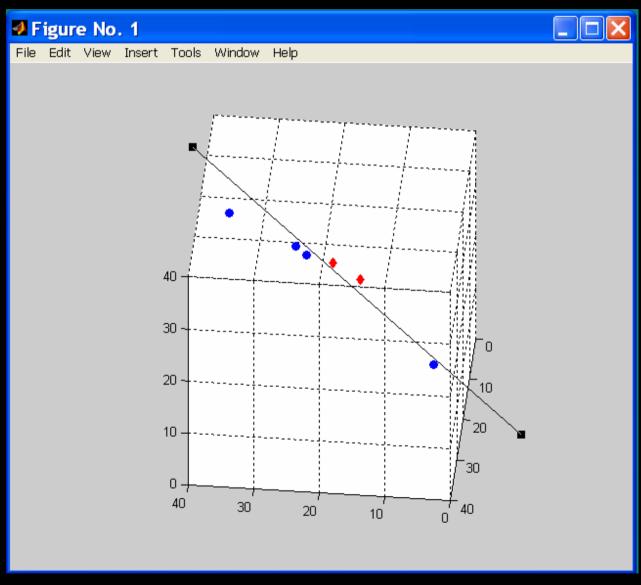
Example:

$$\Phi: \mathbf{R}^2 \to \mathbf{R}^3$$

 $\mathbf{x} = (x_1, x_2), \quad \Phi(\mathbf{x}) = (x_1^2, x_2^2, \sqrt{2} x_1 x_2)$

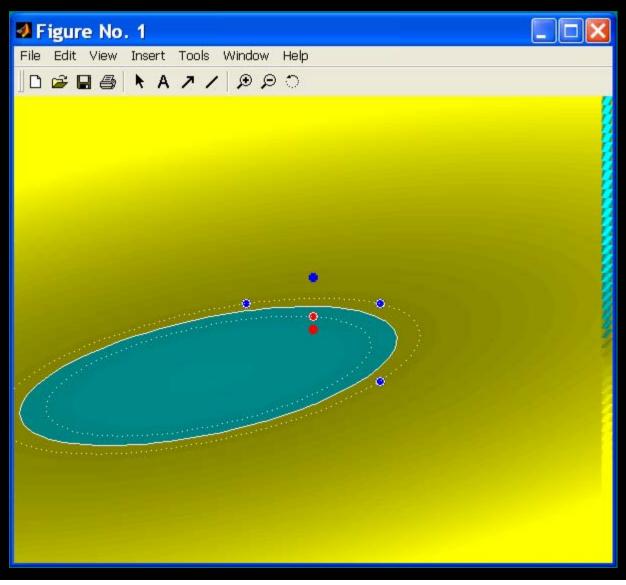
An Example of Linearly Non-Separable Functions

• In case of using the feature space: $\Phi(\mathbf{x}) = (x_1^2, x_2^2, \sqrt{2} x_1 x_2)$



An Example of Linearly Non-Separable Functions

• The corresponding non-linear function in the input space



Kernel Functions

- We need not explicitly map input data into feature space, as the construction of optimal hyperplane and the evaluation of the corresponding decision function only require the the evaluation of dot products $(f(\mathbf{x}) = \text{sgn}(\ \Sigma\ y_i\alpha_i \cdot (\mathbf{x} \cdot \mathbf{x}_i) + b))$
- Therefore, the dot products can be evaluated by a kernel, $k(\mathbf{x}, \mathbf{y})$, such that

$$k(\mathbf{x}, \mathbf{y}) = (\Phi(\mathbf{x}) \cdot \Phi(\mathbf{y}))$$

e.g.
$$k(\mathbf{x}, \mathbf{y}) = (\mathbf{x} \cdot \mathbf{y})^2 = (x_1, x_2, \sqrt{2} x_1 x_2) (y_1, y_2, \sqrt{2} y_1 y_2)^T$$

- Some kernel functions
 - Polynomial : $k(\mathbf{x}, \mathbf{y}) = (\mathbf{x} \cdot \mathbf{y} + 1)^p$
 - Radial basis function : $k(\mathbf{x}, \mathbf{y}) = e^{-\|\mathbf{x} \mathbf{y}\|^2/2\sigma^2}$
 - Neural network : $k(\mathbf{x}, \mathbf{y}) = \tanh(\kappa \mathbf{x} \cdot \mathbf{y} \mathbf{d})$

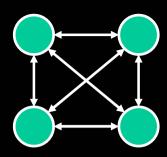
Multiclass SVMs

- SVMs are originally designed to be binary classifiers (discriminating between two classes).
- Thus, SVMs need modification in order to deal with real-world multiclass problems.
- Previous Methods for Multiclass SVMs.
 - One-against-the-Rest (1-v-R)
 - One-against-one (1-v-1)
 - Max Wins algorithm
 - Decision Directed Acyclic Graphs (DDAG)
 - Etc.

One-against-the-Rest

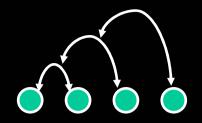
- For *N*-class classification, construct *N* binary classifiers.
- Train the ith classifier with all examples in the ith class as positive, and the other examples as negative labels.
- Output the class corresponding to the classifier with the highest output value.

Max Wins Algorithm



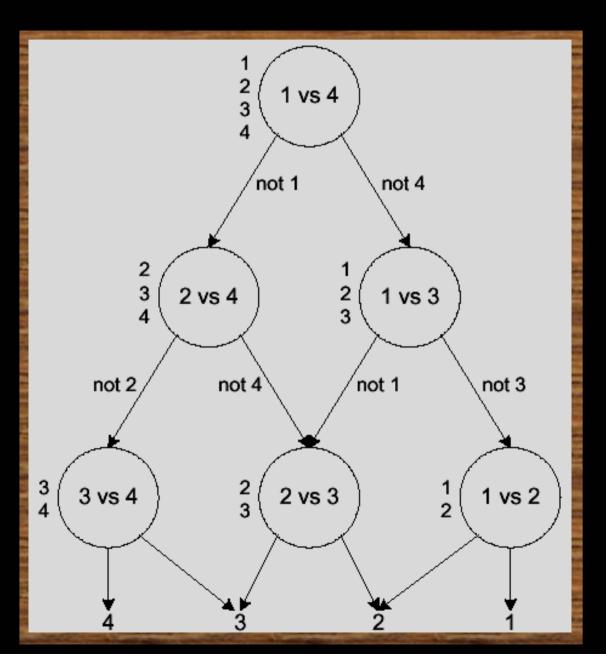
- One-against-one (1-v-1)
 - Construct all possible binary classifiers.
 - For N classes, there will be N(N-1)/2 classifiers.
 - Each classifier is trained on 2 out of N classes.
- Max Wins (a kind of 1-v-1)
 - A test example is classified by all classifiers.
 - Each classifier provides one vote for its preferred class.
 - The majority vote is the final output.
 - Accurate but slow.

DDAG



- Decision Directed Acyclic Graphs
- Concept remove wrong classes one-by-one.
- Construct N(N-1)/2 classifiers, but require only N-1 times of binary classification. (<< N(N-1)/2).
- Faster than Max Wins (require less evaluation time).

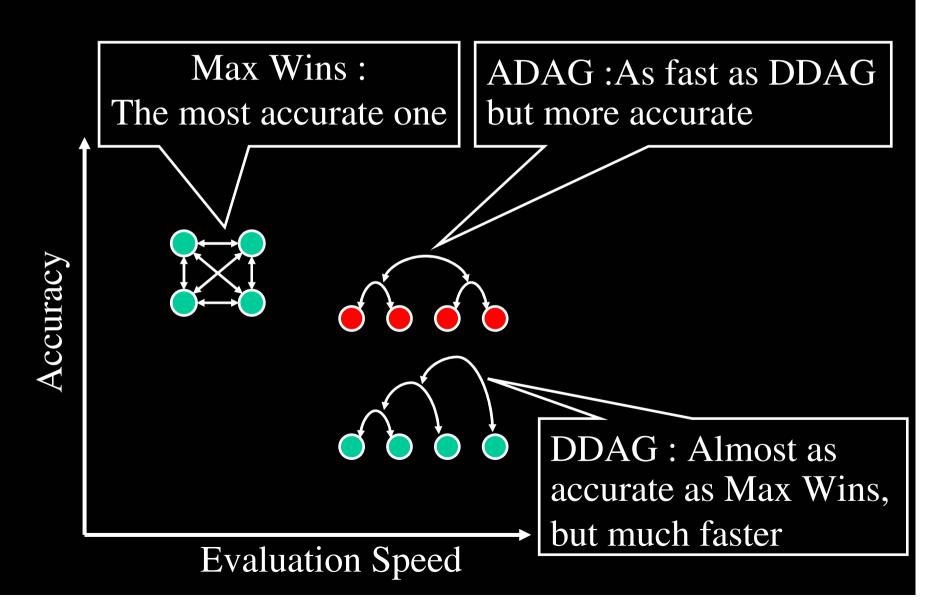
DDAG Architecture



Weakness of DDAG

- Number of node evaluations for the correct class is unnecessarily high.
- If the correct class is evaluated at the root node, it is tested against the other classes for *N*-1 times.
- The higher the number of times the correct class is tested, the higher misclassification will be.

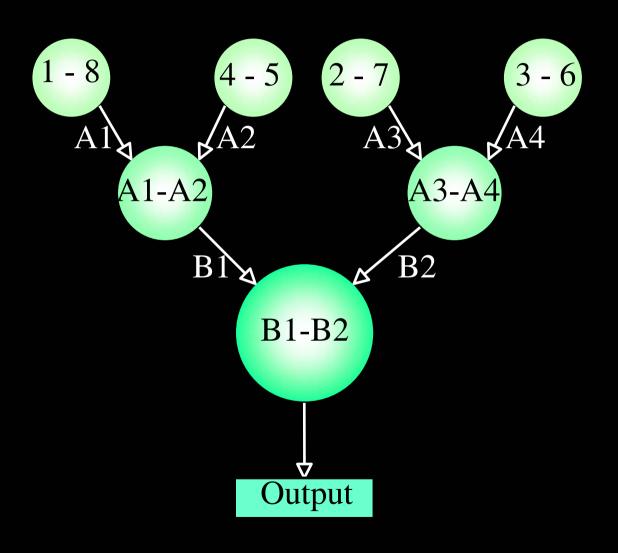
Positioning of Adaptive Directed Acyclic Graphs (ADAG)



ADAG 6

- Adaptive Directed Acyclic Graphs
- The architecture is like a paired knock-out competition.
- In each round, two classes are paired and play a knock-out match.
- The winners proceed to the next round.
- The champion will be the classification result.

ADAG Architecture (8 classes)

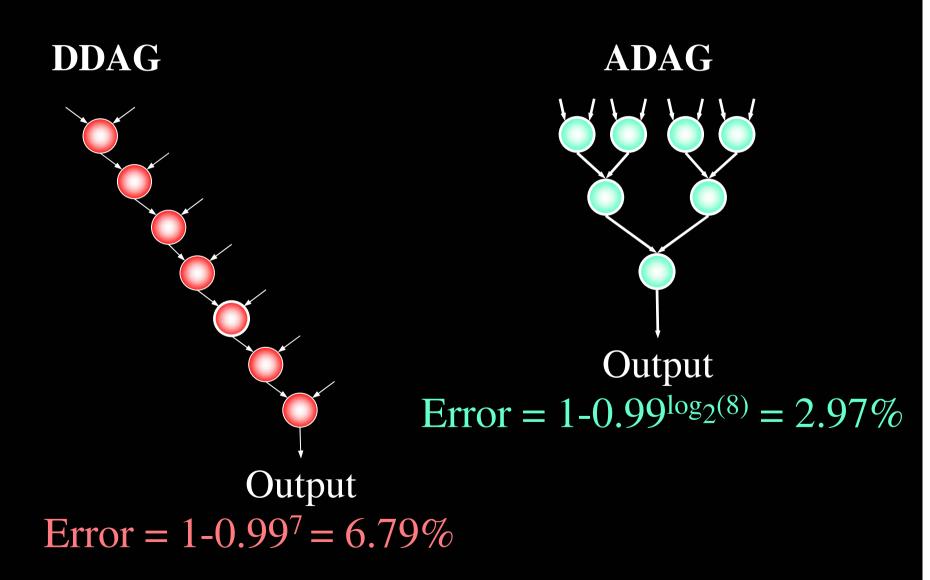


More Accuracy

- ADAG gives higher accuracy than DDAG,
 - when the number of classes increases, and
 - when each binary classifier is not very accurate.
- Reduction of levels of evaluation
 - = Reduction of cumulative error.

More Accuracy

• Suppose each classifier has 1% error rate.



Expected Accuracy of DDAG & ADAG

- Let *p* be the probability that the correct class will be eliminated from the implementation list, when it is tested against another class.
- Let the probability of one of any two classes, except for the correct class, being eliminated from the list be 0.5.
- Assume the probability distribution of the position of the correct class in the list is uniform.
- Let *N* be the number of classes.

Theorems

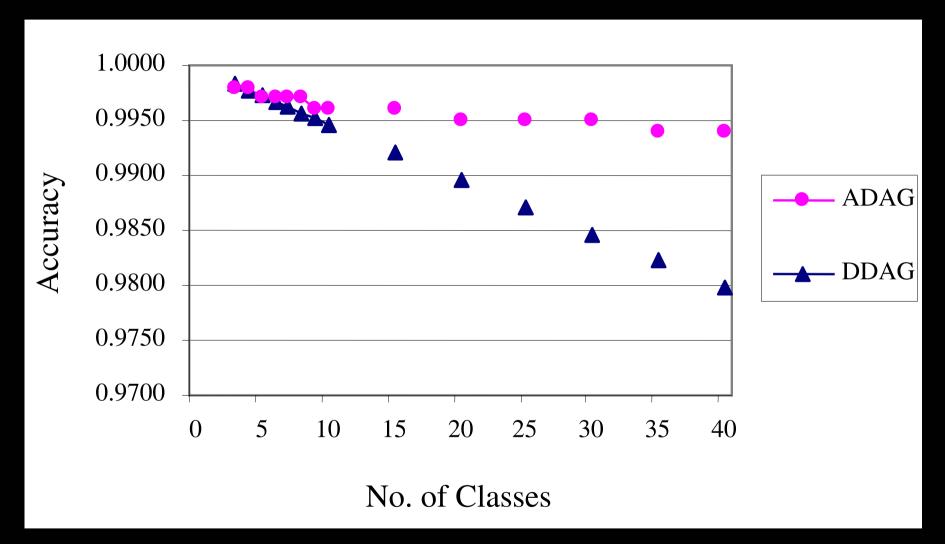
• The expected accuracy of DDAG is

$$\frac{1}{N} \left[\frac{1-p}{p} + (1-p)^{N-1} - \frac{(1-p)^{N}}{p} \right]$$

• The expected accuracy of ADAG is

$$\left(\frac{2N-2^{\lceil\log_2N\rceil}}{N}\right)(1-p)^{\lceil\log_2N\rceil}+\left(\frac{2^{\lceil\log_2N\rceil}-N}{N}\right)(1-p)^{\lceil\log_2N\rceil-1}$$

Expected Accuracy of DDAG & ADAG



p = 0.1%

Experiments

- 2 data sets
 - Thai vowel data set (12 classes)
 - UCI letter data set (26 classes)
- ADAG should have much advantage when the number of classes increases.
- Another factor is the accuracy of binary classifiers (the value of (1-p) in previous theorems).

Experiments: Thai Vowel Data Set

- 12-Class
- Use Polynomial kernel and RBF kernel
 - Polynomial : $|(\mathbf{x} \cdot \mathbf{y} + 1)/72|^d$
 - RBF: $\exp(-|\mathbf{x}-\mathbf{y}|^2/72c)$
- For each value of d or c
 - no. of experiments = 20,000 with several different sequences of classes in the implementation list chosen randomly

Thai Vowel

- No. of training examples: 6,192
- No. of test examples: 3,096

Polynomial					
d	ADAG	DDAG	DIFF		
6	86.12	86.09	0.03		
7	86.12	86.08	0.04		
8	85.98	85.91	0.07		
9	85.39	85.33	0.06		
10	85.09	85.05	0.04		
11	84.58	84.55	0.03		
12	84.30	84.27	0.03		

Thai Vowel (Cont.)

RBF				
С	ADAG	DDAG	DIFF	
0.1	74.32	74.31	0.01	
0.2	84.50	84.48	0.02	
0.3	86.55	86.52	0.03	
0.4	86.77	86.75	0.02	
0.5	86.64	86.63	0.01	

Experiments: UCI Letter Data Set

- 26-Class
- Use Polynomial kernel and RBF kernel
- No. of experiments = 50,000 with several different sequences of classes in the implementation list chosen randomly

UCI Letter

Polynomial				
d	ADAG	DDAG	DIFF	
1	83.83	83.31	0.52++++	
2	95.59	95.17	0.42++++	
3	95.96	95.51	0.45++++	
4	95.88	95.46	0.42++++	
5	95.83	95.34	0.49++++	
6	95.35	94.87	0.48++++	
7	94.78	94.25	0.53++++	
8	93.83	93.14	0.69++++	
9	93.22	92.45	0.77++++	
10	92.42	91.62	0.80++++	

^{• ++++} denotes 99.99% confidence level for difference

UCI Letter (Cont.)

RBF					
С	ADAG	DDAG	DIFF		
0.1	90.81	90.64	0.17++		
0.2	94.13	93.97	0.16+++		
0.3	95.46	95.36	0.10++		
0.4	96.31	96.21	0.10++		
0.5	96.48	96.39	0.09++		
0.6	97.03	96.97	0.06+		
0.7	97.28	97.22	0.06+		
0.8	97.20	97.15	0.05+		

- +++ denotes 99.00% confidence level for difference
- ++ denotes 95.00% confidence level for difference
- denotes 90.00% confidence level for difference

UCI Letter (Cont.)

RBF					
С	ADAG	DDAG	DIFF		
0.9	97.27	97.22	0.05+		
1.0	97.38	97.34	0.04		
1.5	97.59	97.55	0.04		
2.0	97.63	97.62	0.01		
2.5	97.76	97.76	0.00		
3.0	97.91	97.90	0.01		
3.5	97.84	97.84	0.00		
4.0	97.80	97.79	0.01		

^{• +} denotes 90.00% confidence level for difference